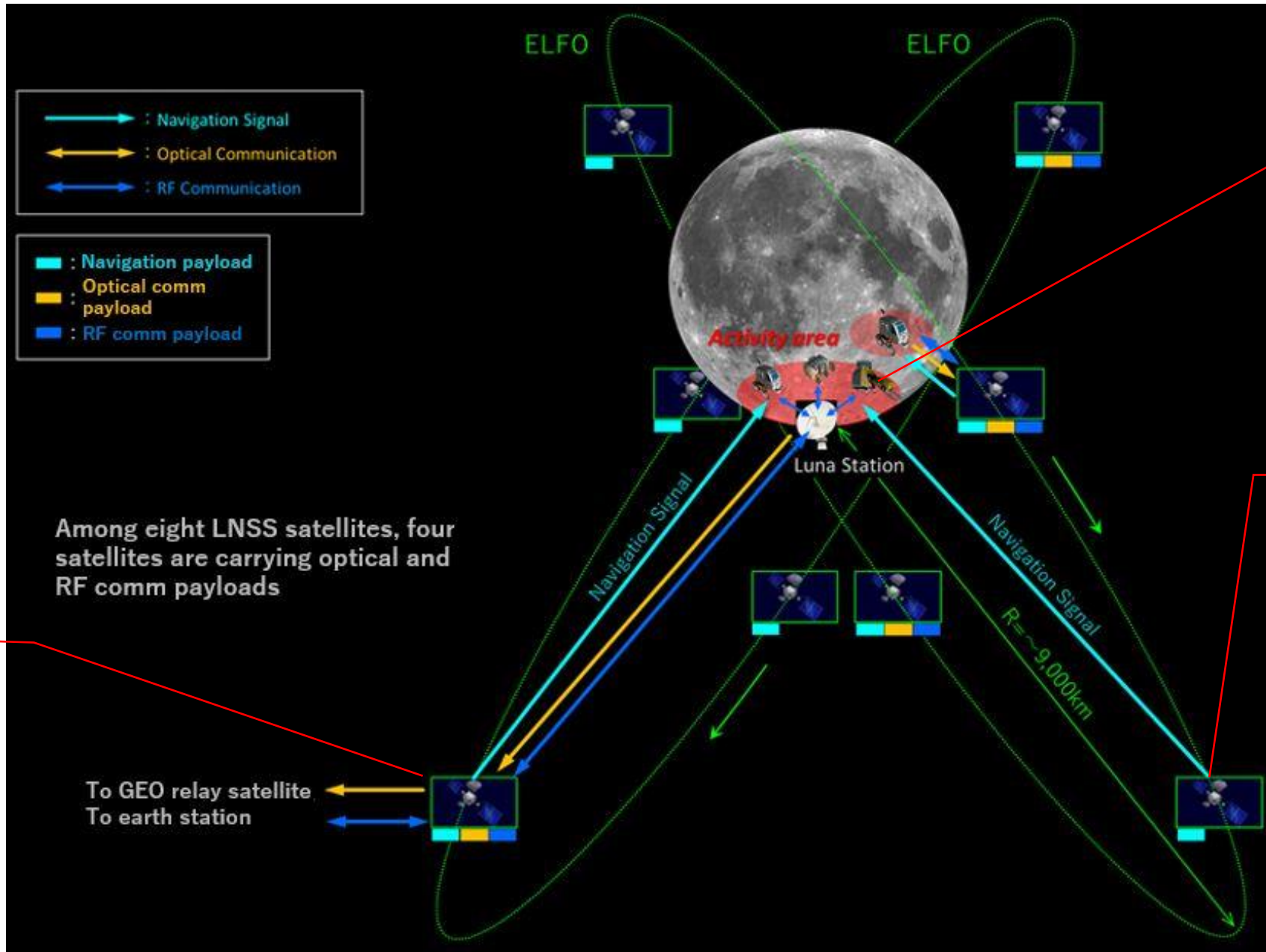




Japan, USA, EU, China
plans for Lunar PNT and
international collaboration

Masaya Murata (JAXA)

LNSS is GPS-like satellite system for the moon designed by JAXA

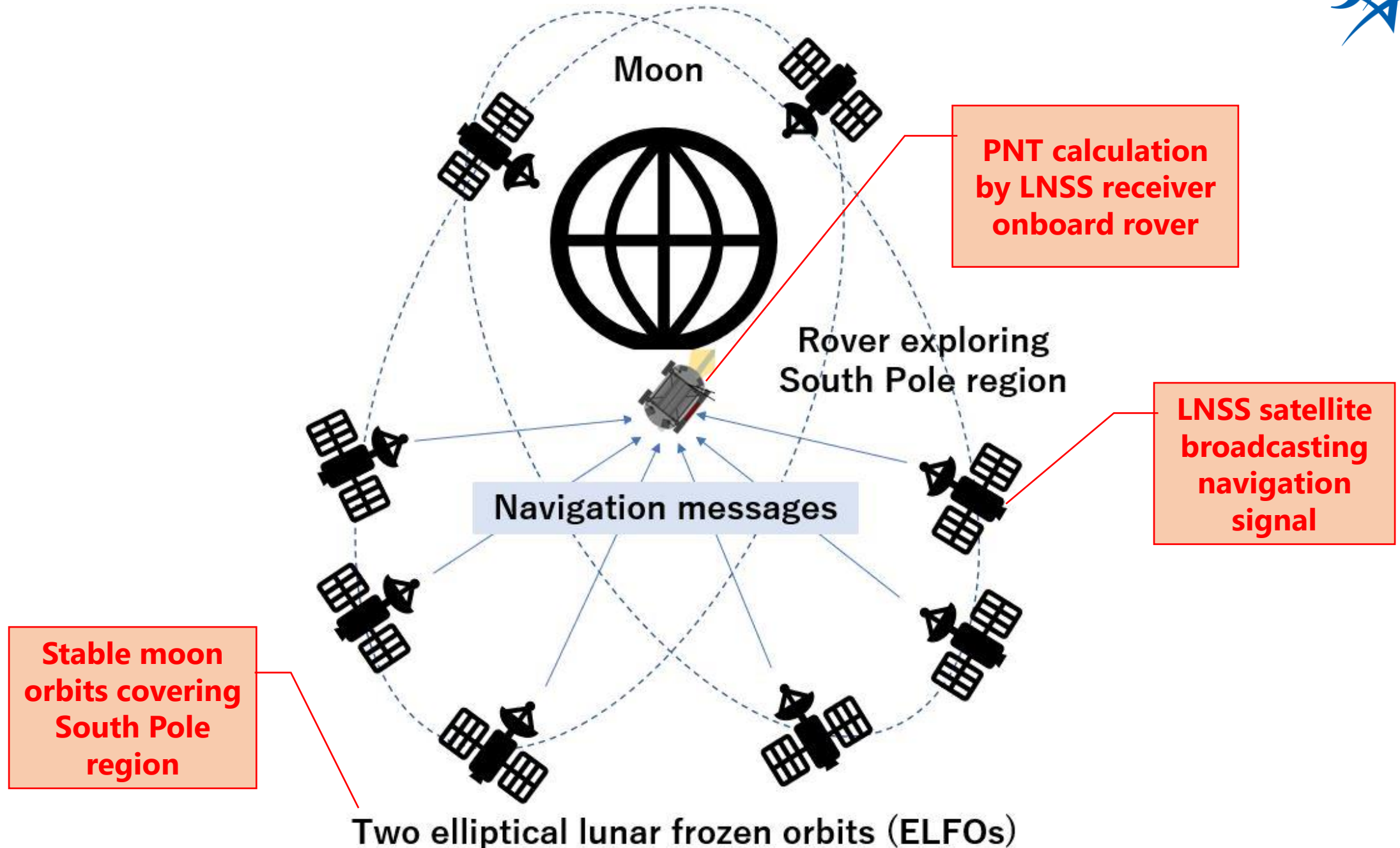


LNSS satellite functioning as data relay satellite

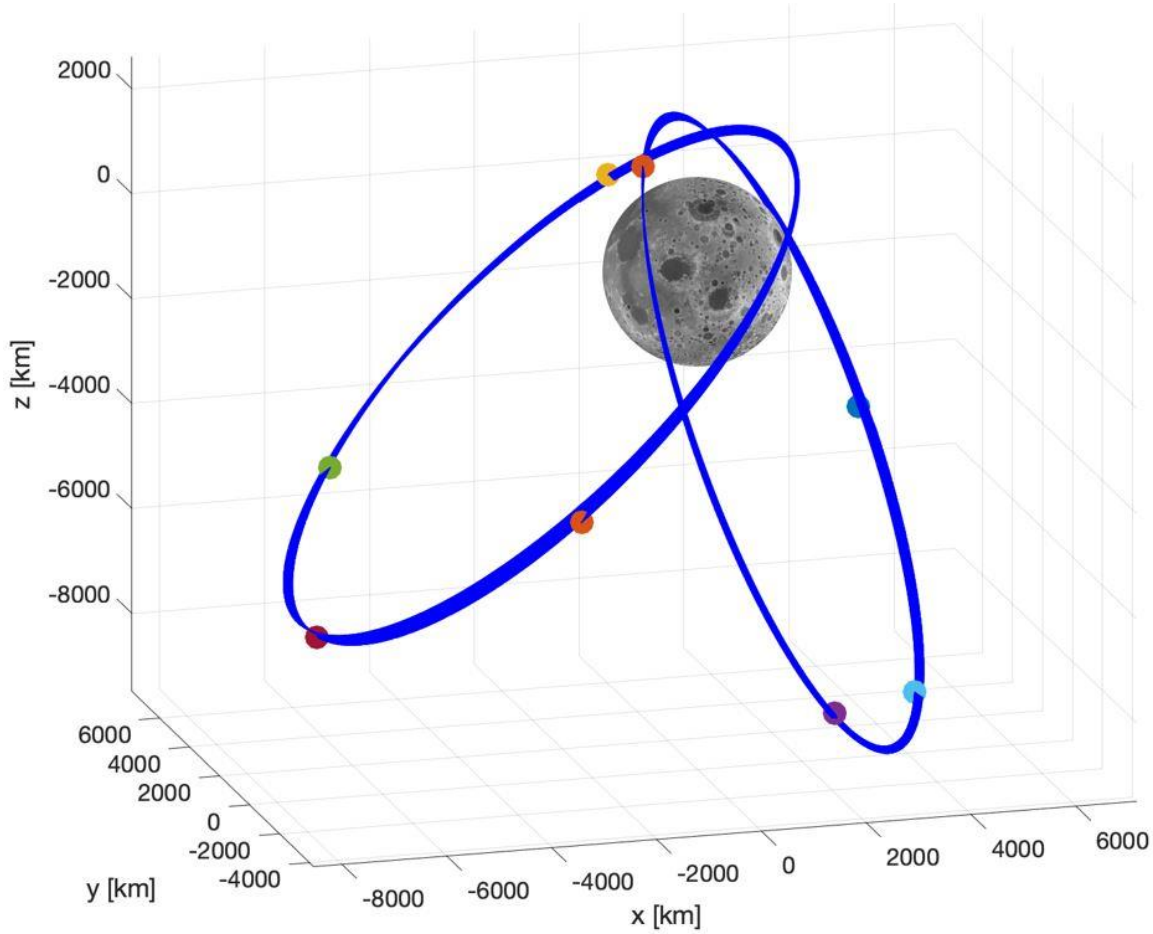
Target: South Pole region

LNSS satellite broadcasting navigation signal

LNSS real-time PNT service at South Pole region

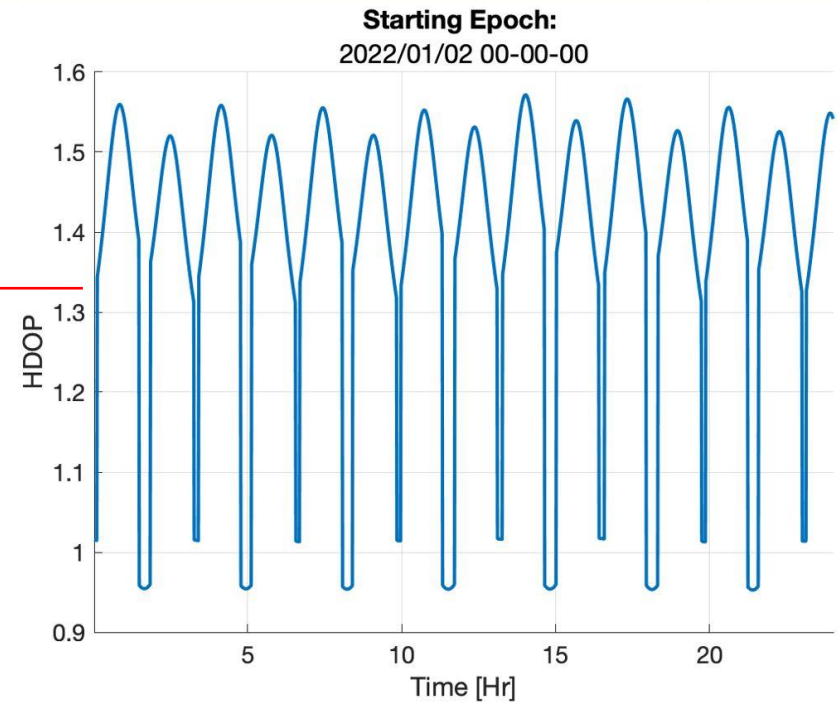


LNSS satellite constellation for South Pole region

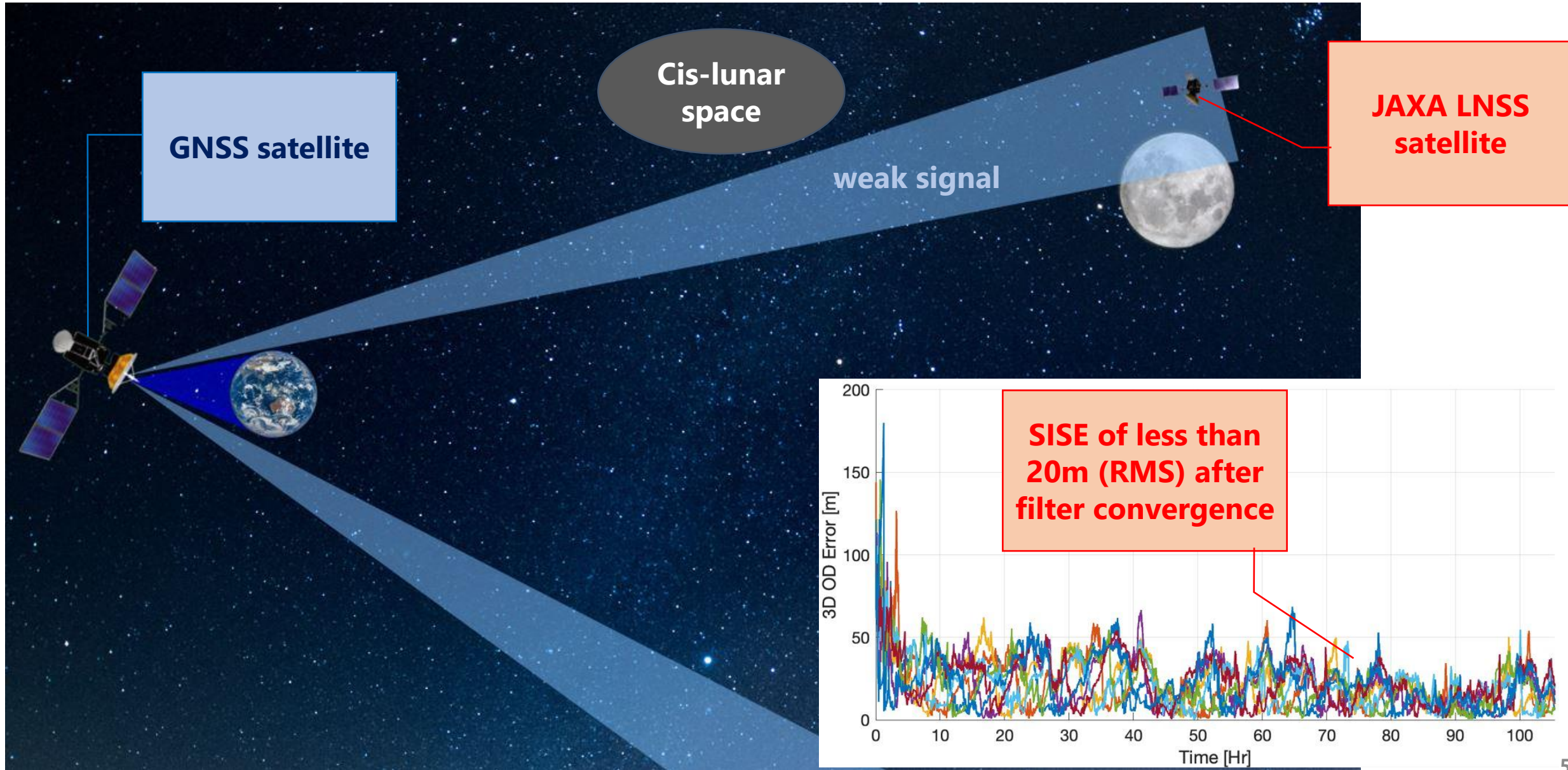


SV	A[km]	E	I[deg]	RAAN[deg]	AP[deg]	MA[deg]
ELFO11	6540	0.6	56.2	0	90	0
ELFO12	6540	0.6	56.2	0	90	90
ELFO13	6540	0.6	56.2	0	90	180
ELFO14	6540	0.6	56.2	0	90	270
ELFO21	6540	0.6	56.2	180	90	45
ELFO22	6540	0.6	56.2	180	90	135
ELFO23	6540	0.6	56.2	180	90	225
ELFO24	6540	0.6	56.2	180	90	315

HDOP of around 1.3 always at South Pole region



GNSS navigation (real-time OD) for LNSS satellites, making the LNSS autonomous



Expected single point positioning (SSP) accuracy at the South Pole (Our requirement is **< 40m** in terms of the horizontal (2D) positioning accuracy)

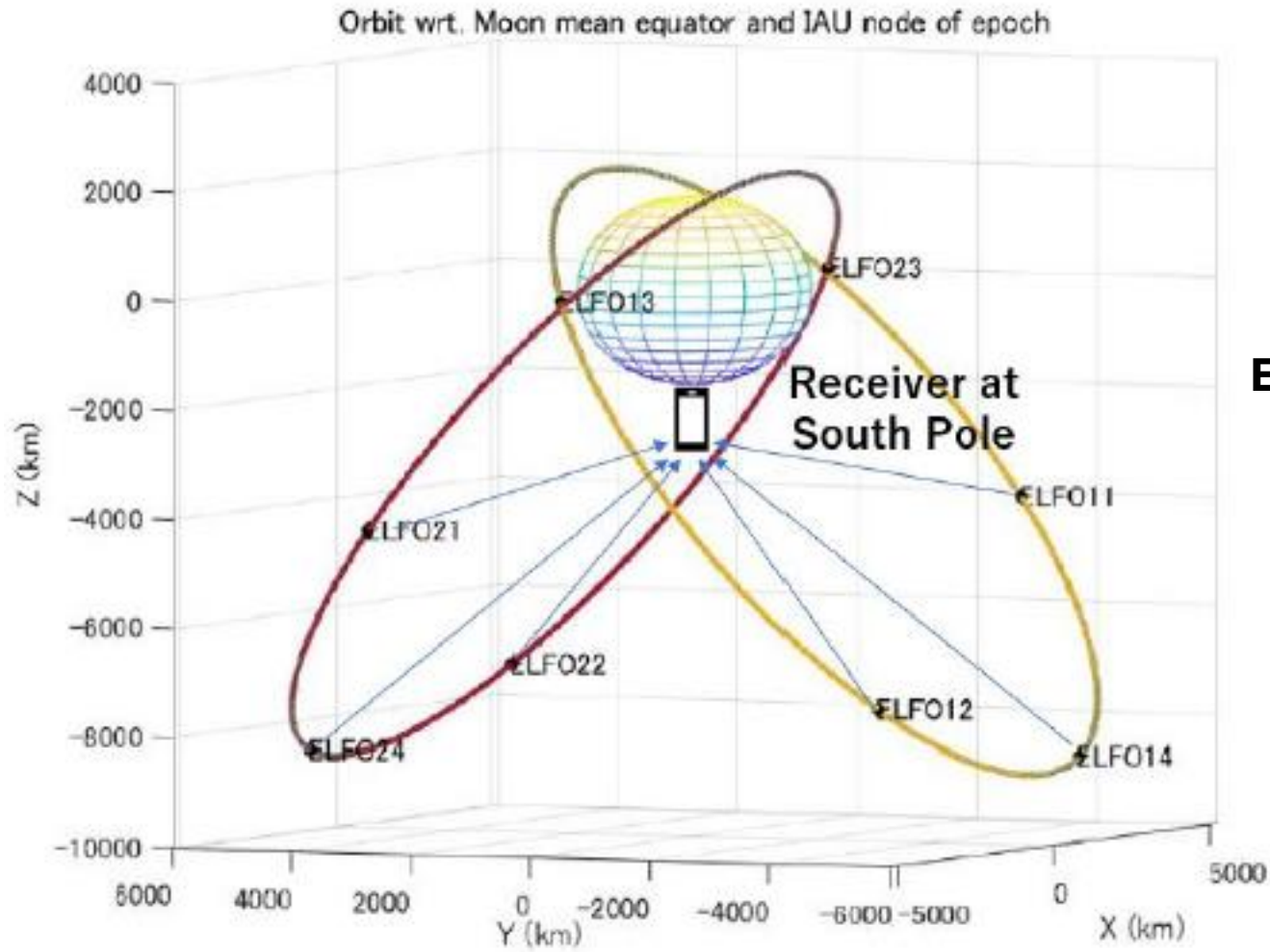
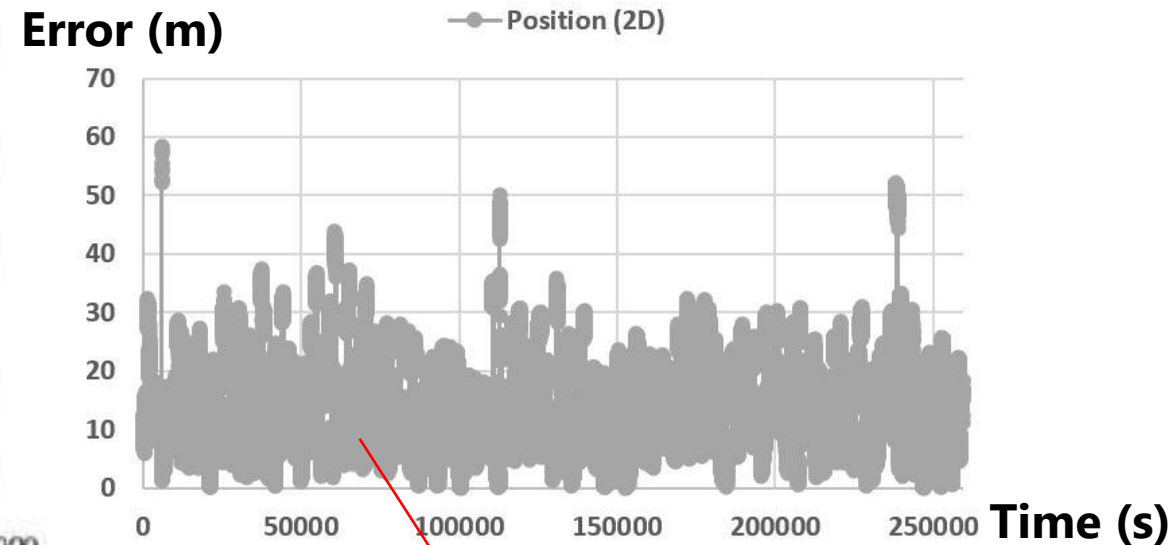


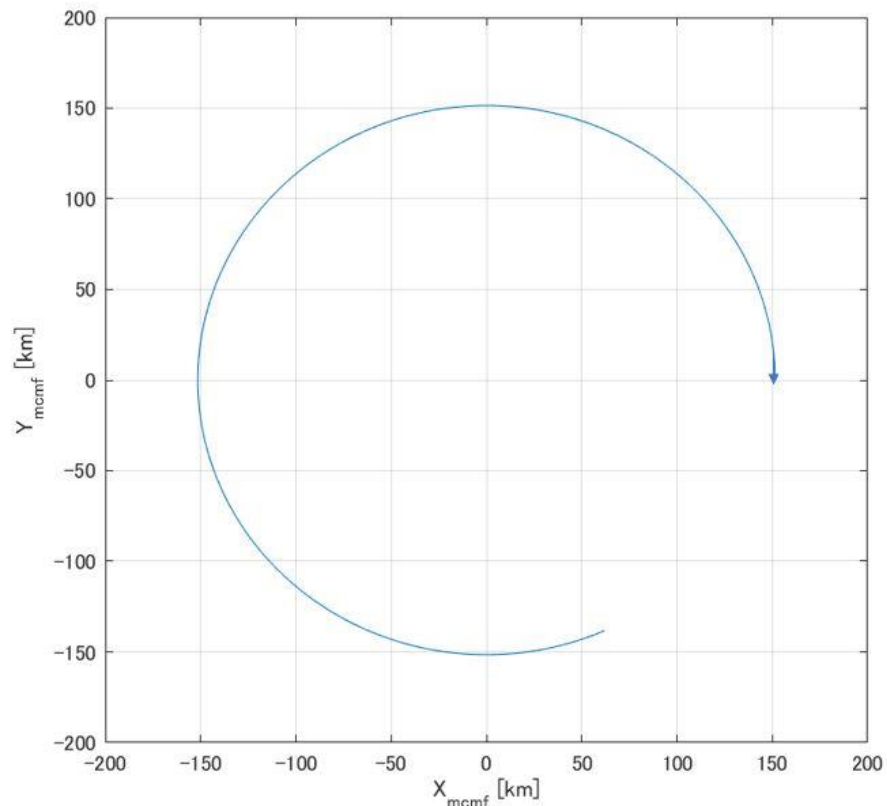
Figure 2: LNSS satellite constellation and receiver at South Pole.

- Average SSP errors:
3D position 37.7m,
2D position 13.8m,
Vertical 32.8m,
Clock bias 6.6E-08s



Less than 40m for most of the epochs

Expected navigation accuracy for moving object such as pressurized rover (Our requirement is **< 10m** in terms of the horizontal (2D) positioning accuracy)

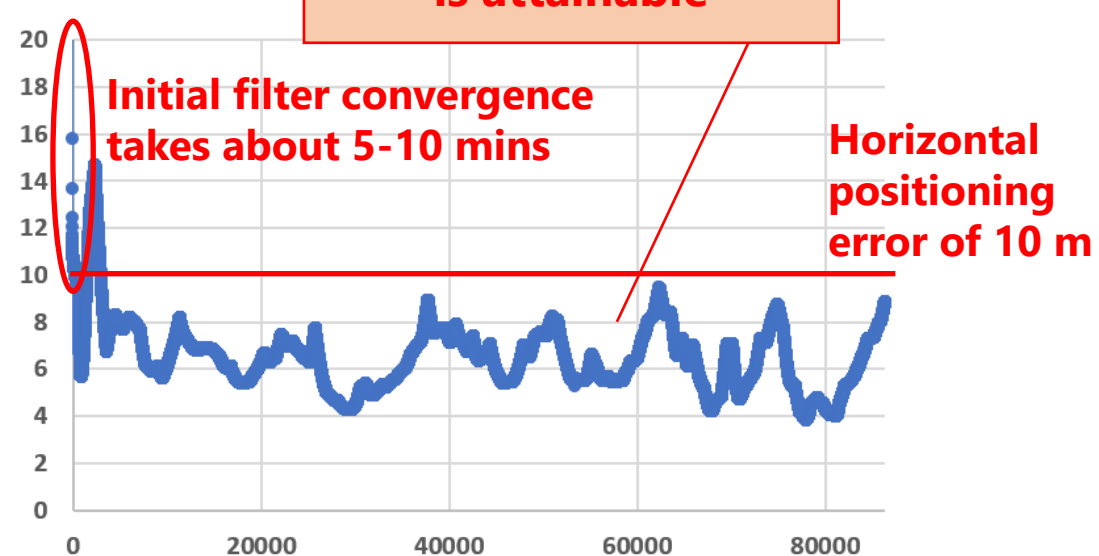
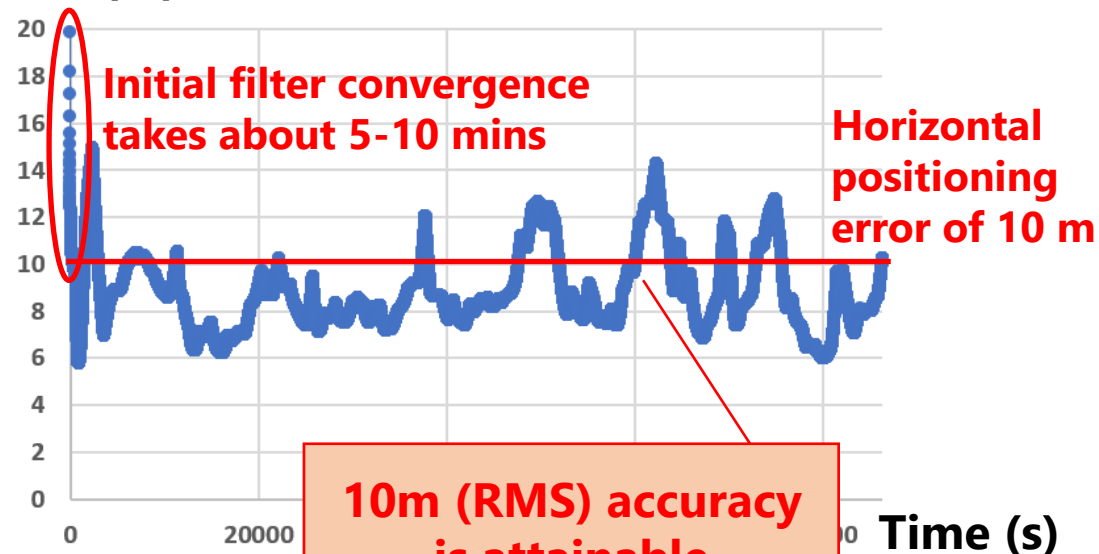


Circular movement with a velocity of 3m/s at the south latitude of 85°

➔
LNSS + high-grade IMU (1Hz measurements)

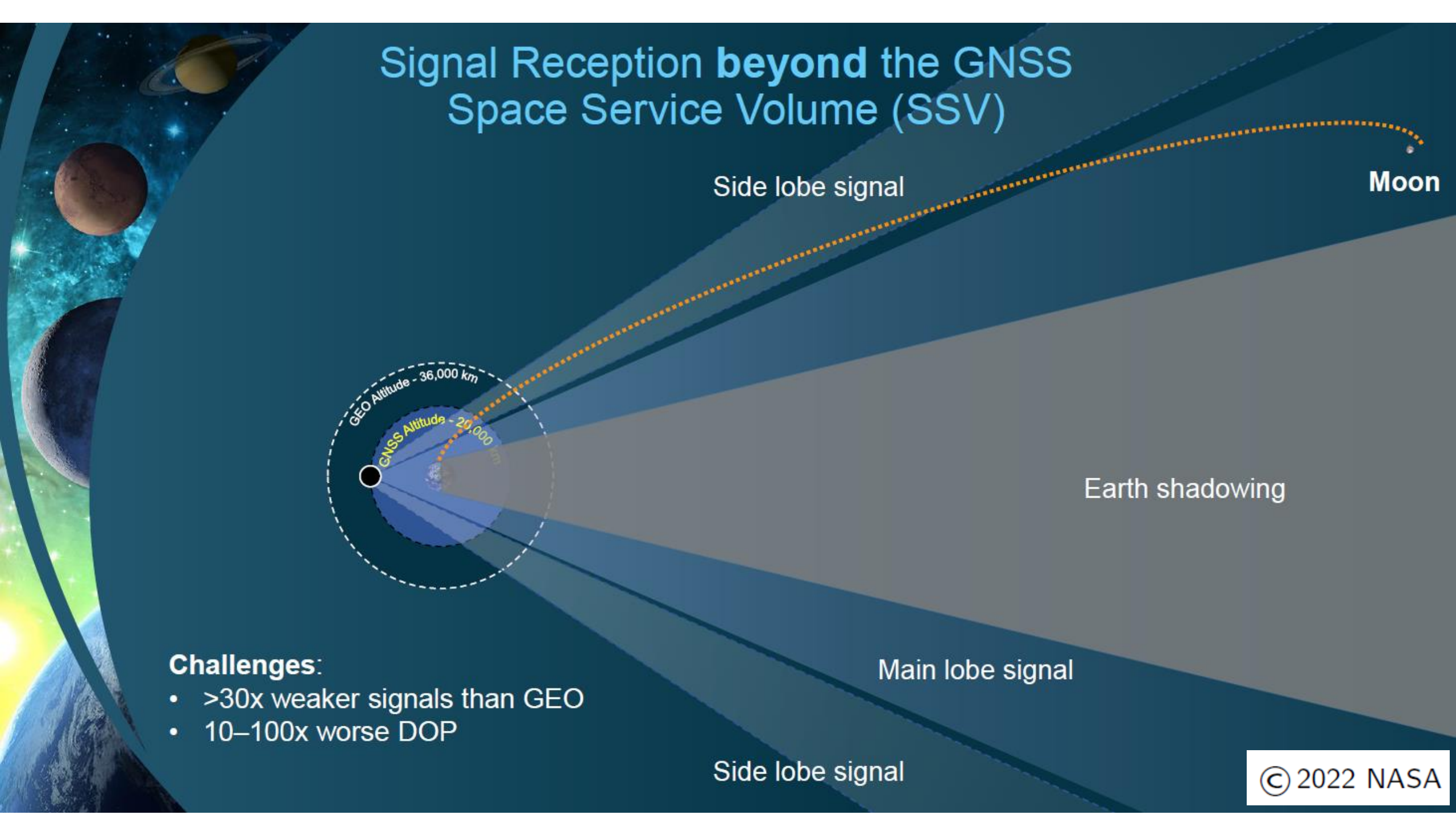
➔
LNSS + high-grade IMU (10Hz measurements)

Error (m)



NASA Status

Signal Reception **beyond** the GNSS Space Service Volume (SSV)



Side lobe signal

Moon

GEO Altitude - 36,000 km

GNSS Altitude - 20,000 km

Earth shadowing

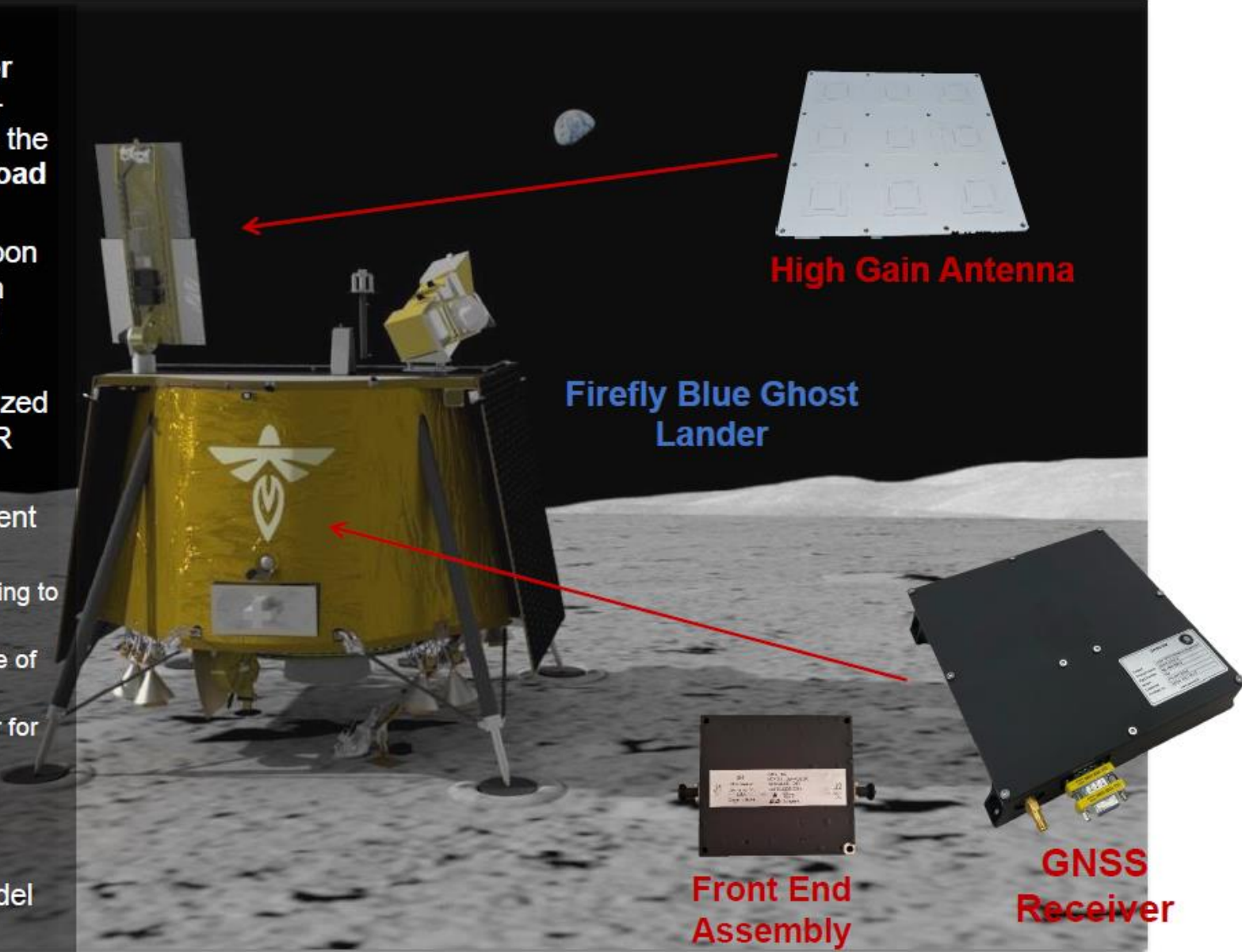
Challenges:

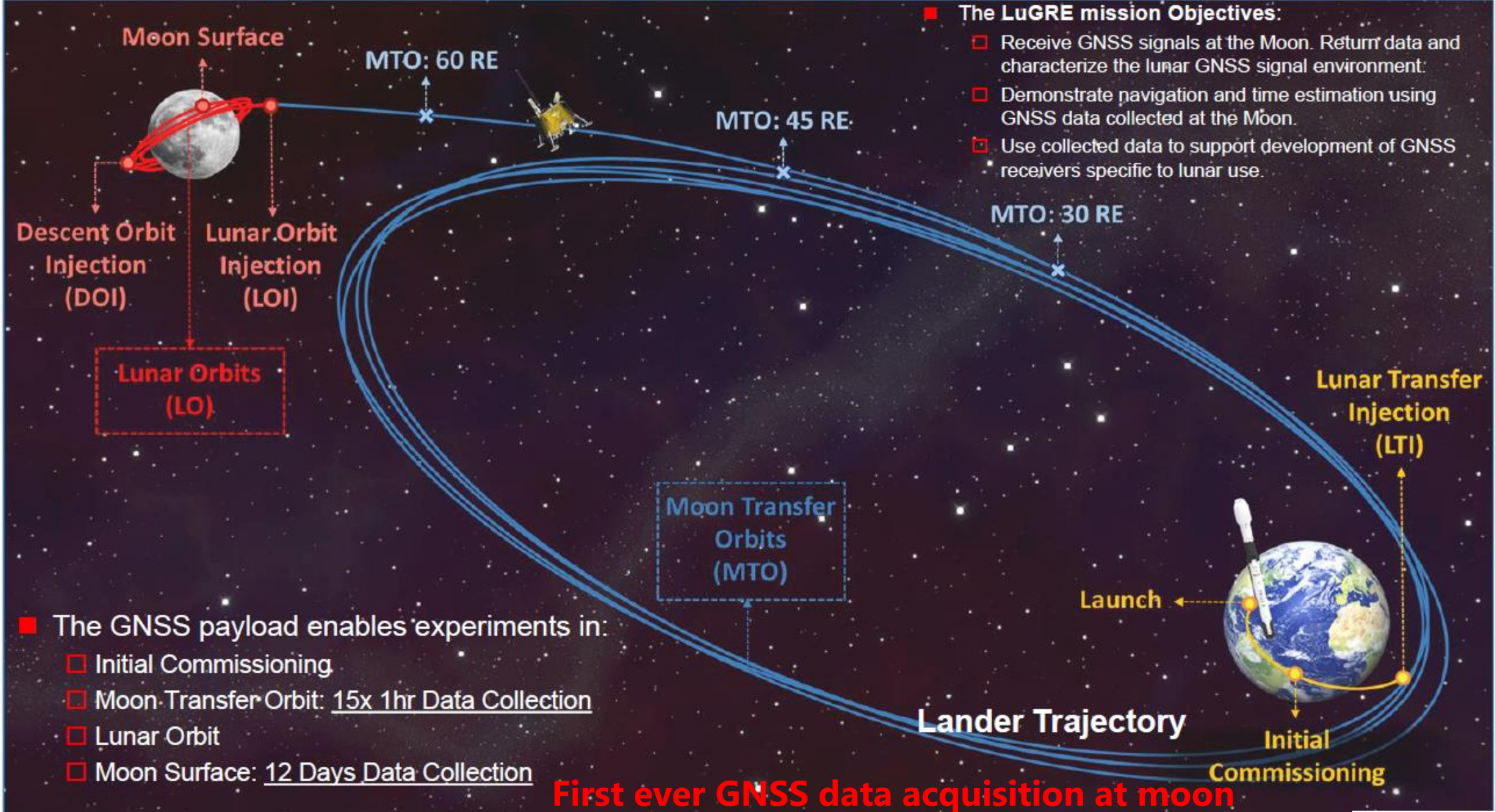
- >30x weaker signals than GEO
- 10–100x worse DOP

Main lobe signal

Side lobe signal

- Qascom is the provider of the GNSS Payload for the **Lunar GNSS Receiver Experiment (LuGRE)**, under a NASA-Italian Space Agency (ASI) initiative in the frame of the **Commercial Lunar Payload Services (CLPS)**
- The Payload will fly and land to the Moon (Mare Crisium 18°N, 62°E) in **2024** on board the Firefly Blue Ghost Mission 1 (BGM1)
- The GNSS payload is a Moon customized version of Qascom QN400-Space SDR receiver (GPS/GAL, L1/L5).
- The main challenges of the Development have been:
 - ❑ Maximize GNSS Data Collection according to LuGRE Mission Operational Concept
 - ❑ Deliver a Payload matching the schedule of the BGM1 Commercial Mission
 - ❑ Improve the Robustness of the Receiver for the Lunar Radiation Environment
 - ❑ Upgrade the Receiver High Sensitivity Processing and Positioning for Moon scenarios
- To date, the GNSS Payload Flight Model is undergoing Acceptance Testing





- **The LuGRE mission Objectives:**
 - Receive GNSS signals at the Moon. Return data and characterize the lunar GNSS signal environment.
 - Demonstrate navigation and time estimation using GNSS data collected at the Moon.
 - Use collected data to support development of GNSS receivers specific to lunar use.

- **The GNSS payload enables experiments in:**
 - Initial Commissioning
 - Moon Transfer Orbit: 15x 1hr Data Collection
 - Lunar Orbit
 - Moon Surface: 12 Days Data Collection

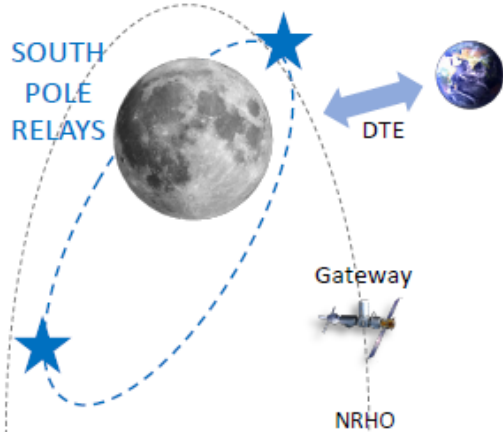
First ever GNSS data acquisition at moon

Overview of Architecture Evolution

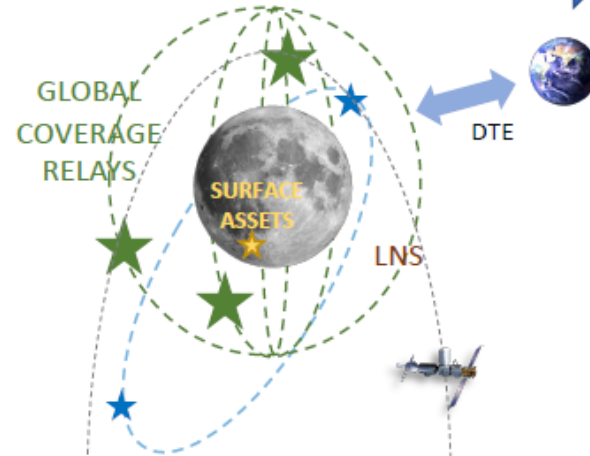
Initial Phase: By **2024-2026**

Growth Phase: **2027-2030**

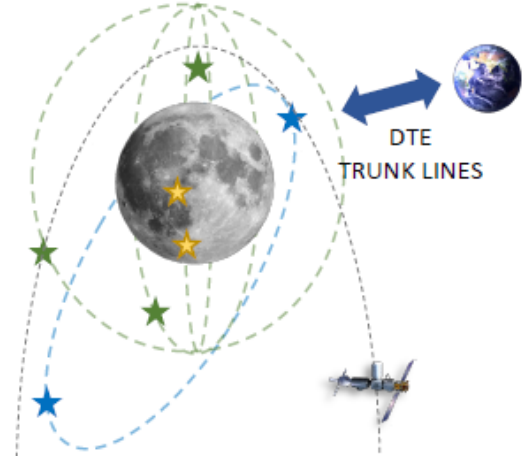
Desired Future State: 2030 + Beyond



- DTE service for Near Side, lunar orbiters and surface missions
- Intensive relay service for South Pole and a selected area of the Far Side
- Initial PNT service and lunar surface networks
- LunaNet interoperability established from the beginning



- Continued DTE service for Near Side
- Expanded relay service for South Pole and multiple Far Side regions
- Limited relay service for other globally-dispersed locations and orbiters
- Lunar Navigation Service for PNT
- Surface networking
- Introduction of optical links

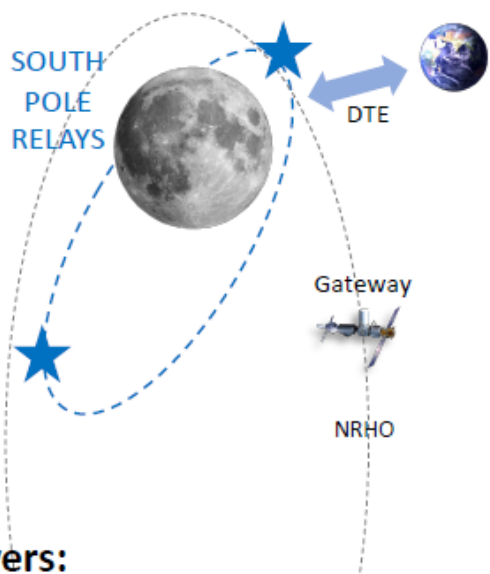


- Satellite constellations with multiple operators functioning as cooperative set of networks
- Intensive coverage of specific regions and regular coverage of all regions
- Optical trunk line links
- Surface network assets in multiple locations

The implementation described is not intended to be prescriptive but to indicate a means to achieve the required services. Other implementations that would meet the same intent should be considered.

Initial Phase Architecture

Initial Phase: By 2024-2026



Mission Drivers:

- Multiple spacecraft, orbiting and landed, requiring DTE service
- Far-side robotic users and human exploration at the South Pole
- High-rate services up to 50 Mbps return and 10 Mbps forward
- PNT knowledge for landed spacecraft to within 100 meters

Implementation:

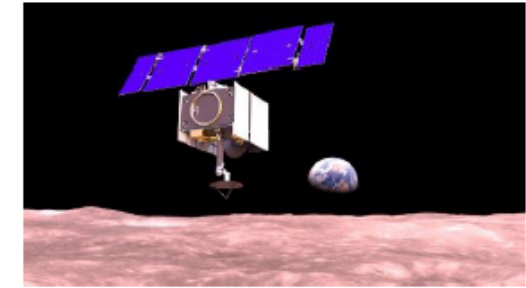
- LEGS assets supplemented by DSN when necessary for DTE service needs
- At least two Relay satellites in an elliptical orbit to provide service to the South Pole and a portion of the Far Side.
- As possible, additional relay satellites added for greater capacity and redundancy.
- Relay satellite systems comply with established **interoperability standards**
- **PNT service** from relay satellites to include, as a minimum, range and range rate service as part of communications link and incorporation of Earth-orbit-based GNSS reception and precise on-board time reference for position knowledge
- As possible, relay satellites should incorporate capabilities for direct links between lunar users and **intersatellite links** between relay satellites.
- **Gateway** and **ESA Lunar Pathfinder** may also contribute to relay capabilities.

Initial Relay Concept

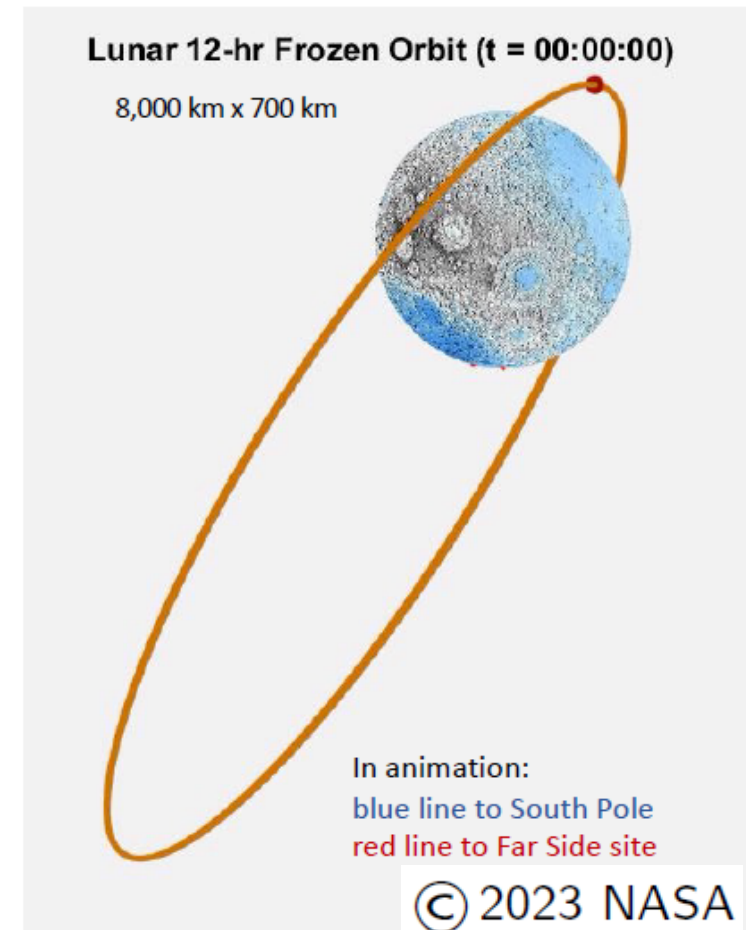
Lunar Communications Relay and Navigation Systems (LCRNS), Lockheed Martin's Parsec to be launched in 2025

For the initial architecture, coverage of South Pole and southern region of the Far Side is needed

- There is a family of elliptical orbits that require minimal orbit maintenance and provide long dwell times over the South Pole
 - A single relay satellite in a 12-hour elliptical orbit can provide 8 to 9 hours of coverage of South Pole and Schrodinger Basin (Far Side reference site) in each orbit - yielding about 75% coverage time
 - With only two properly phased relays in this type of orbit, South Pole coverage could be continuous, independent of Gateway.
- Small spacecraft – as low as 150-300 kg could be adequate for the service needed. These could be delivered as rideshare payloads.
- Relays would link to Earth ground stations – assuming 18-meter class antennas.
- Gateway, when present, will provide substantial relay service to HLS missions
- ESA Lunar Pathfinder may provide service to NASA robotic science missions.
- Over time, more satellites can be added in order to augment redundancy, increase capacity for more users, and expand to global coverage.

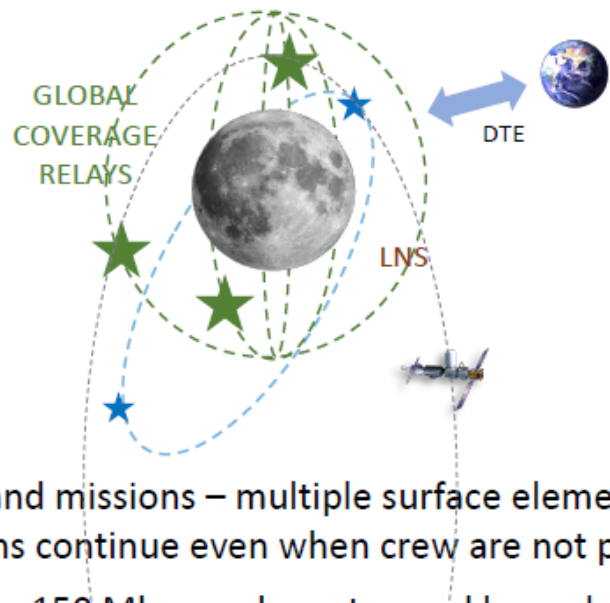


Reference Relay Concept



Growth Phase Architecture

Growth Phase: 2027-2030



Mission Drivers:

- Growth in assets and missions – multiple surface elements (e.g., LTV) and operations continue even when crew are not present
- Data rate growth to 150 Mbps and greater, and lower latency services for real-time telerobotic operations
- Growth in mobility operations – distance and durations
- More diversity in mission location across a range of far side and polar regions with longer durations
- Science missions and EVA crew will require very precise position information and on-demand location service
- Lunar orbiting spacecraft demand is likely to increase substantially, including many small satellites

Implementation:

- Maintain relay service in elliptical orbit over South Pole with addition and/or replenishment of satellites, as needed. Capacity of individual relay satellites or combined capacity of multiple satellites increase.
- Establish 3GPP/5G surface communications and navigation assets to maintain contact between surface elements and between mobile elements and orbiting relays or Earth.
- Add relay satellites to provide globally-distributed coverage.
- DTE service needs will peak as lunar relay satellites and surface relays will **aggregate data and provide trunk lines to Earth.**
- Coherent **Optical links** might be introduced: 1) for trunk lines between lunar relays and Earth stations, 2) for intersatellite links between relays, and 3) between lunar relays and lunar users.
- Comprehensive PNT services with the introduction of “Lunar Navigation Service” (LNS) comparable to the Earth-based GNSS.
- Additional ground station capacity via commercial service contracts and international partner contributions.

Their IOC will potentially split into three phases: Inc-Alpha, Inc-Bravo, Inc-Charlie

Initial Operating Capability Increments

	Increment-Alpha	Increment-Bravo	Increment-Charlie
Effectivity	2025	2027	2028
Capabilities	<ul style="list-style-type: none"> •Communication support •RF and waveform compatibility with LNIS •AFS 	<ul style="list-style-type: none"> •Enhanced communications support •RF and waveform compatibility with LNIS •Multiple AFS 	<ul style="list-style-type: none"> •Full set LCRNS SRD IOC requirements
% of SRD IOC RQMTS	75%	83%	100%

LNIS: LunaNet Interoperability Specification; AFS: Augmented Forward Signal (PNT);

Their on-orbit service testing is in 2025 and service validation is in 2028

Validation Milestone	Milestone Title	Potential Timeframe
M1	Service Concept	2023
M2	Service Requirements	
M3	Service Design	2024
M4	Service Integration	
M5	On-Orbit Service Testing	2025
M6	On-Orbit Service Verification	2027
M7	On-Orbit Service Validation	2028

Phase-Increment	Inc-Alpha			Inc-Bravo				Inc-Charlie		
	Ka-band	S-band	AFS	Ka-band	S-band	AFS		Ka-band	S-band	AFS/ LANS
Service Type										
Number of simultaneous links	1	1	1	1	1	2	3	2	2	4
Forward/Return Link	R only	F+R	F only	F+R	F+R	F only	F only	F+R	F+R	F only
Service Volume	SV1			SV1				SV2		
Min. % Coverage of an Earth Day	70% (TBR)			75%	90%	70%	40%	75%	90%	40% (with max. spatial GDOP<6)

A possibility that there will be four NASA (LCRNS) satellites in 2028

ESA Status

STEP 1: LUNAR PATHFINDER

Low-rate satellite communications service + Moon GNSS Receiver

Development



Pathfinder Service

⇒ Q4 2025

STEP 2: MOONLIGHT CONSTELLATION

High-data rate satellite communications and navigation service

Design

Development



IOC



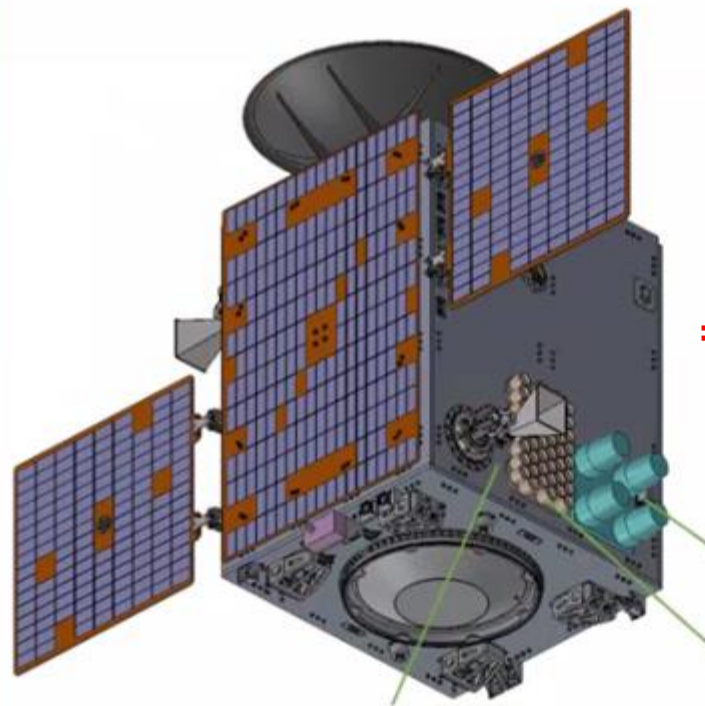
FOC

2020 2021 2022 2023 2024 2025 2026 2027 2028 2030



© 2022 ESA

Lunar Pathfinder Satellite – First ever GPS/GALILEO reception on lunar orbit

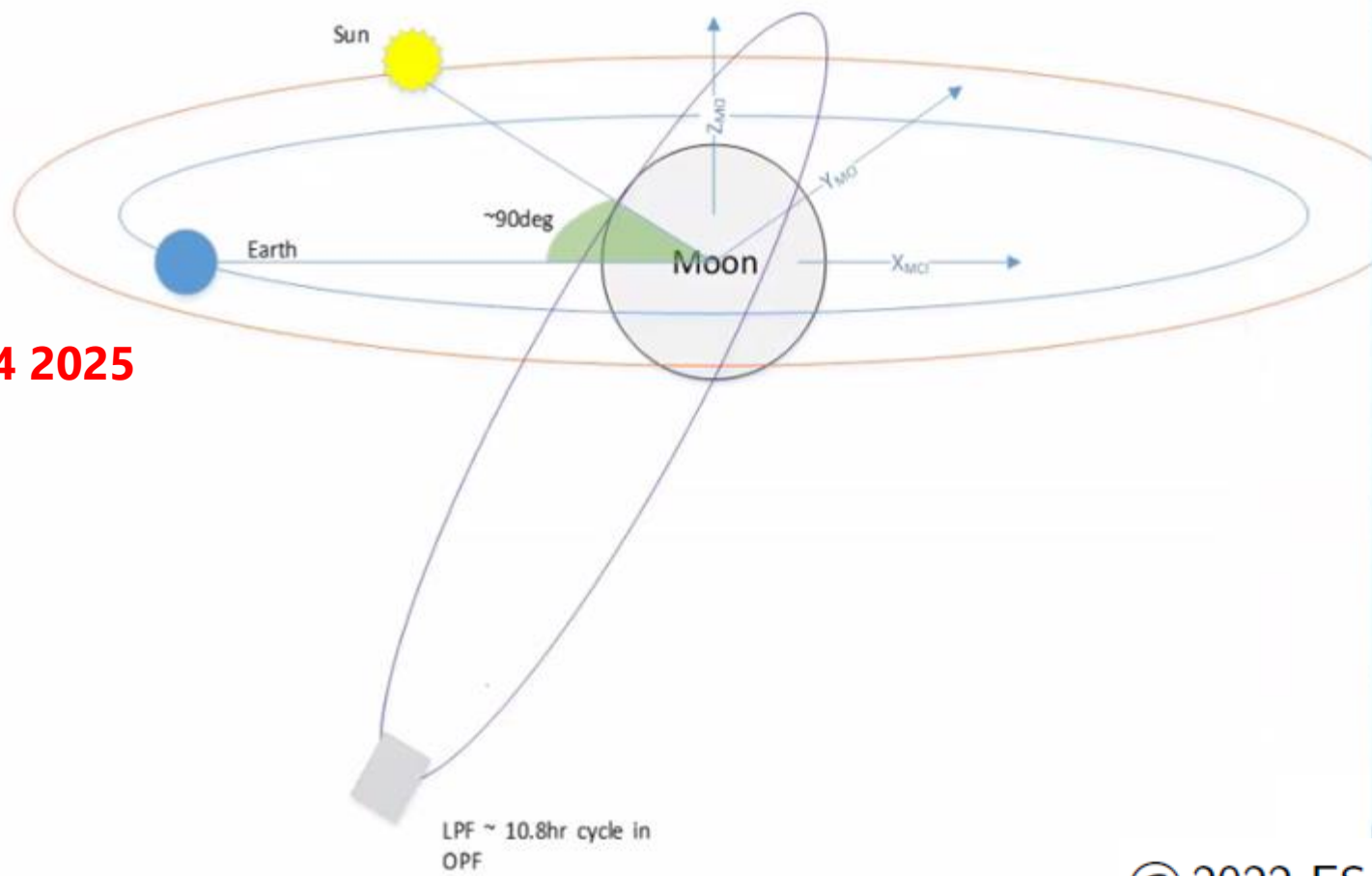


X-Band High Gain Antenna

Laser Retroreflector

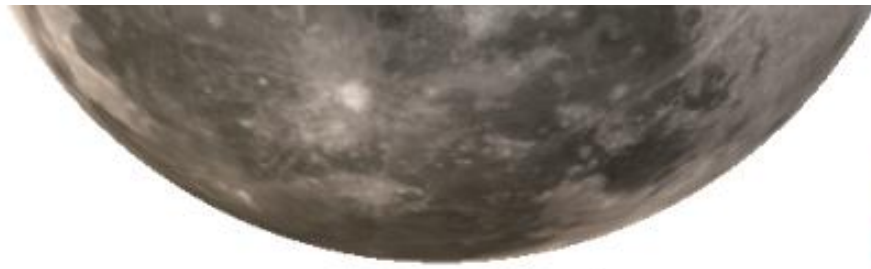
GNSS Antenna

⇒ launch in Q4 2025



© 2022 ESA





Lunar Pathfinder Capabilities

User return data-rates:

- **Earth Link**
 - 5Mbps X-band
- **Moon Link***
 - 8Mbps S-band
 - 4Mbps UHF

*depending on location and user performance



X-Band Earth Link



S-Band Moon Link



UHF Moon Link



Laser Retro Reflector



GNSS Weak Signal Detection



Radiation Monitor

Communications

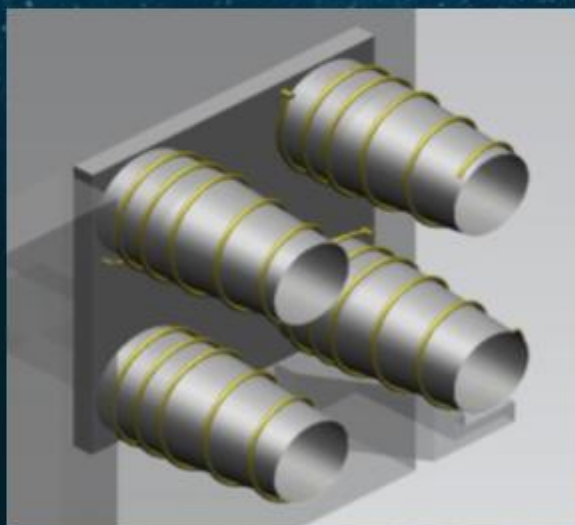
Hosted Payloads

Lunar Pathfinder experiment – GNSS receiver



Parameter	Value
Acquisition sensitivity	15dBHz
Tracking sensitivity	15dBHz
3D Position accuracy	< 100m RMS
3D Velocity accuracy	< 0.1 m/s RMS
Mass	1.3 Kg
Size	24x12x7cm
Power	< 12W
Constellations	GPS / Galileo L1/E1/L5/E5

SpacePNT NaviMoon Receiver Specifications

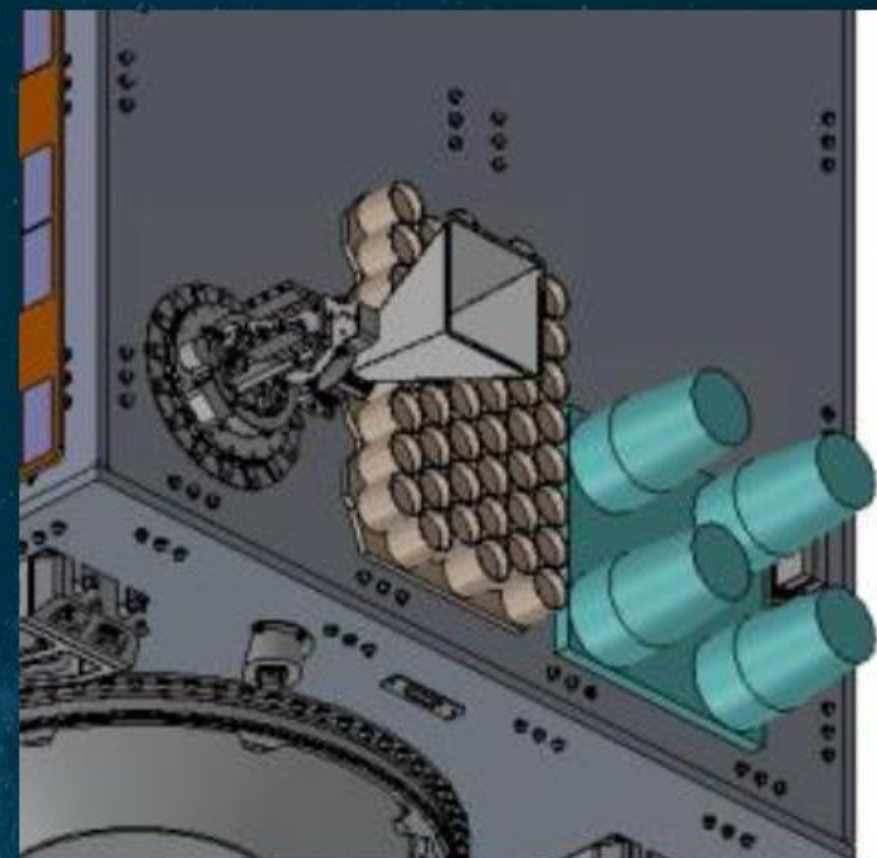
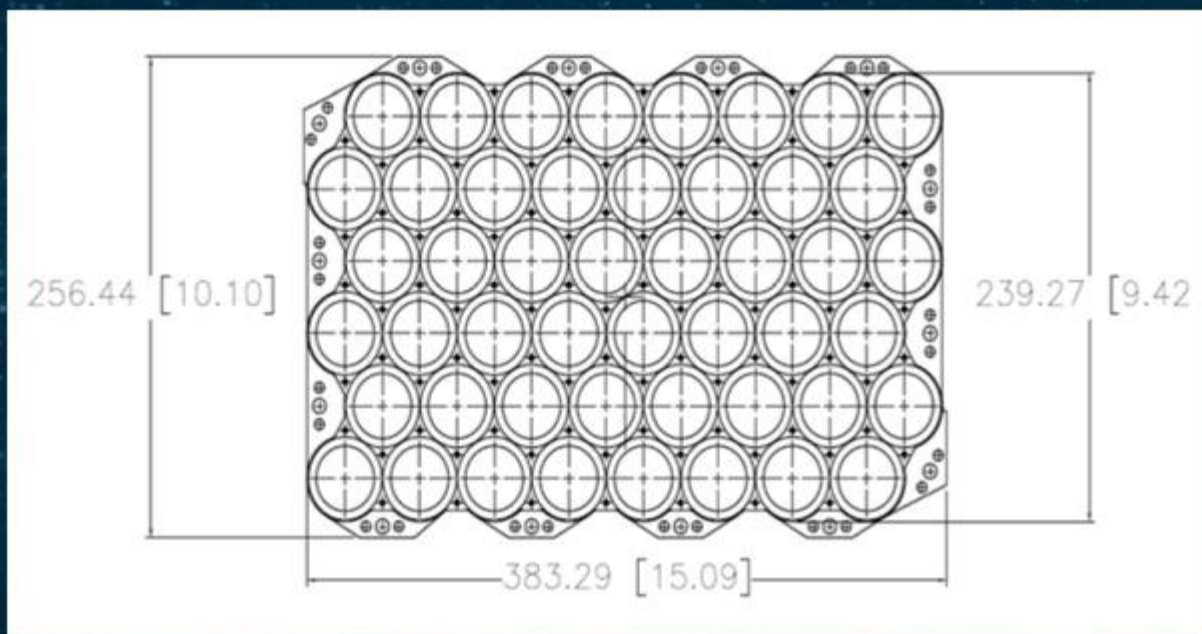


Parameter	Value
L1 boresight gain	15 dBi
L5 boresight gain	12 dBi
Polarization	RHCP
Mass	~2Kg
Size	26x26x28cm

MDA Antenna Specifications © 2022 ESA

First ever demonstration of GNSS reception on Lunar orbit.

LRR Developed by NASA



Technical Description:

- LRR is composed of 48 reflector cubes (1.6" diameter), based on the technology developed and flown by NASA on the Lunar Reconnaissance Orbiter (LRO) - Mass < 4 kg (TBC)

First time ever three ranging techniques (GNSS, Laser and X-band ranging) are used simultaneously on lunar orbit

Mid term - Moonlight IOC

- IOC phase will start by end of 2027 with at least one satellite transmitting the one-way (AFS) navigation signal
- Signal will be compliant with LunaNet requirements ensuring interoperability (same user terminal can work with multiple LNSP with minor SW modifications)
- Orbits will be defined by the service provider, however ELFO orbits are expected (e.g.: 24h orbit period)



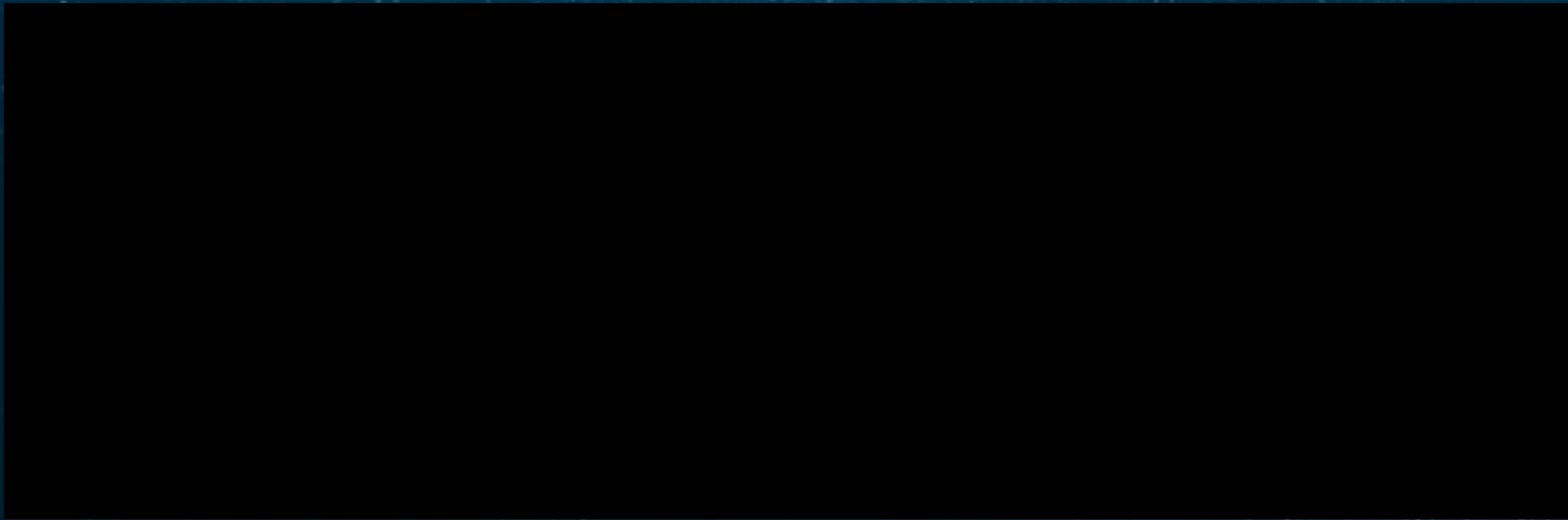
From LNIS:

*The **SISE** is defined as the instantaneous difference between the position, velocity and time of a LunaNet satellite as broadcast by the LunaNet node navigation message and the true satellite position, velocity and time, respectively expressed in the lunar reference frame [AD5] and the lunar system time reference [AD6].*

LCNS NAV service main targets (IOC)	
Requirement	Value
SISE	< 20m 95%
OWR availability	> 80%

Long term - Moonlight FOC

- Moonlight FOC phase will start by end of 2030
- PVT service has to be provided so LCNS should have around 4 satellites transmitting the one-way (AFS) navigation signal
- Signal will be compliant with LunaNet requirements ensuring interoperability (same user terminal can work with multiple LNSP with minor SW modifications)
- Orbits will be defined by the service provider, however ELFO orbits are expected (e.g.: 24h orbit period)



LCNS NAV service Main requirements	
Requirement	Value
Geographic coverage	South Pole
Temporal availability	15h/24h
PVT availability	> 95%

China Status

2023 International Conference of Deep Space Sciences

22-27 April 2023, Hefei, China

22-27 April 2023

Home

Important dates

Program

Registration



中華人民
共和国

西安市
Xi'an

2-3 hours by
express train

Hefei

Shanghai

成都市
Chengdu

Expected single point positioning (SSP) accuracy at the South Pole
(Our requirement is < 40m in terms of the horizontal (2D) positioning accuracy)

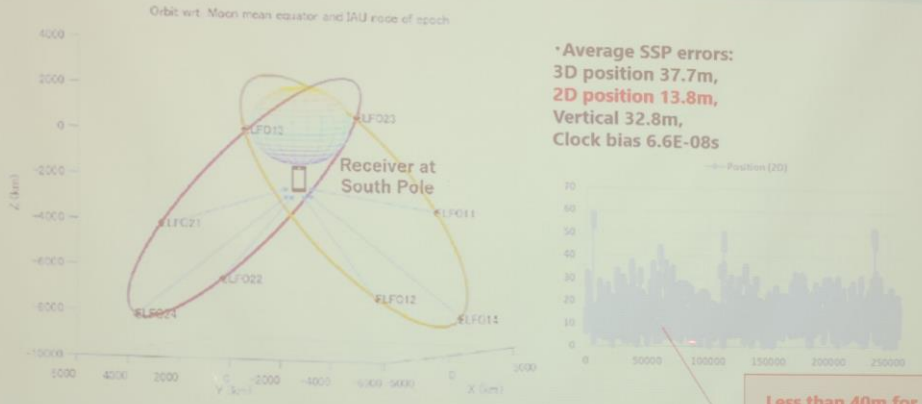


Figure 2: LNSS satellite constellation and receiver at South Pole.

Presented our LNSS (Lunar Navigation Satellite System) and its demonstration mission plan



Queqiao (QQ)-Net plan

2030年前

Queqiao V1.0

基本建成地月空间通信能力
验证网络、导航等关键技术，
主要服务于探月四期、国际月
球科研站等任务等

速率：50Mbps, 10Gbps (验证)
定位精度：100m (验证)

2040年前

Queqiao V2.0

■ 全面建成地月空间通导能力
■ 实现区域导航，服务于载人月
球探测、国际月球探测等

速率：1~10Gbps
定位精度：50m

2050年前

Queqiao V3.0

■ 建成深空通导星座基本型
■ 实现火星、金星通信导航覆盖，
服务于火星探测、金星探测和
太阳系边界探测等

速率：>10Gbps
定位精度：优于10m

鹊桥通导遥综合星座系统

(简称Queqiao)

China's lunar
comm&nav system
called Queqiao (鹊桥)

~2030

50Mbps return, 100m positioning accuracy

2030~2040

1~10Gbps return, 50m positioning accuracy

2040~2050

>10Gbps return, 10m positioning accuracy

Chang'e (嫦娥)- 6 in 2024

Chang'e 7 in 2026

Chang'e 8 in 2028

International Lunar Research Station (ILRS)



Moon exploration

Planet exploration

Sun exploration

Queqiao-2 will be launched in early 2024 to support Chang'e-6, 7, and 8

Tiandu (天都)-1, 2 will be launched together with Queqiao-2 for comm&nav experiment

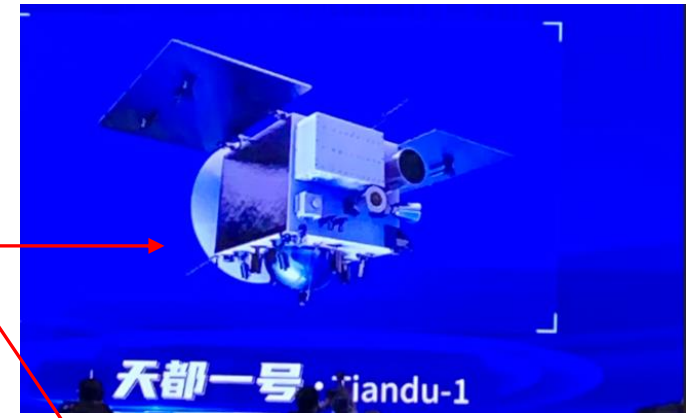
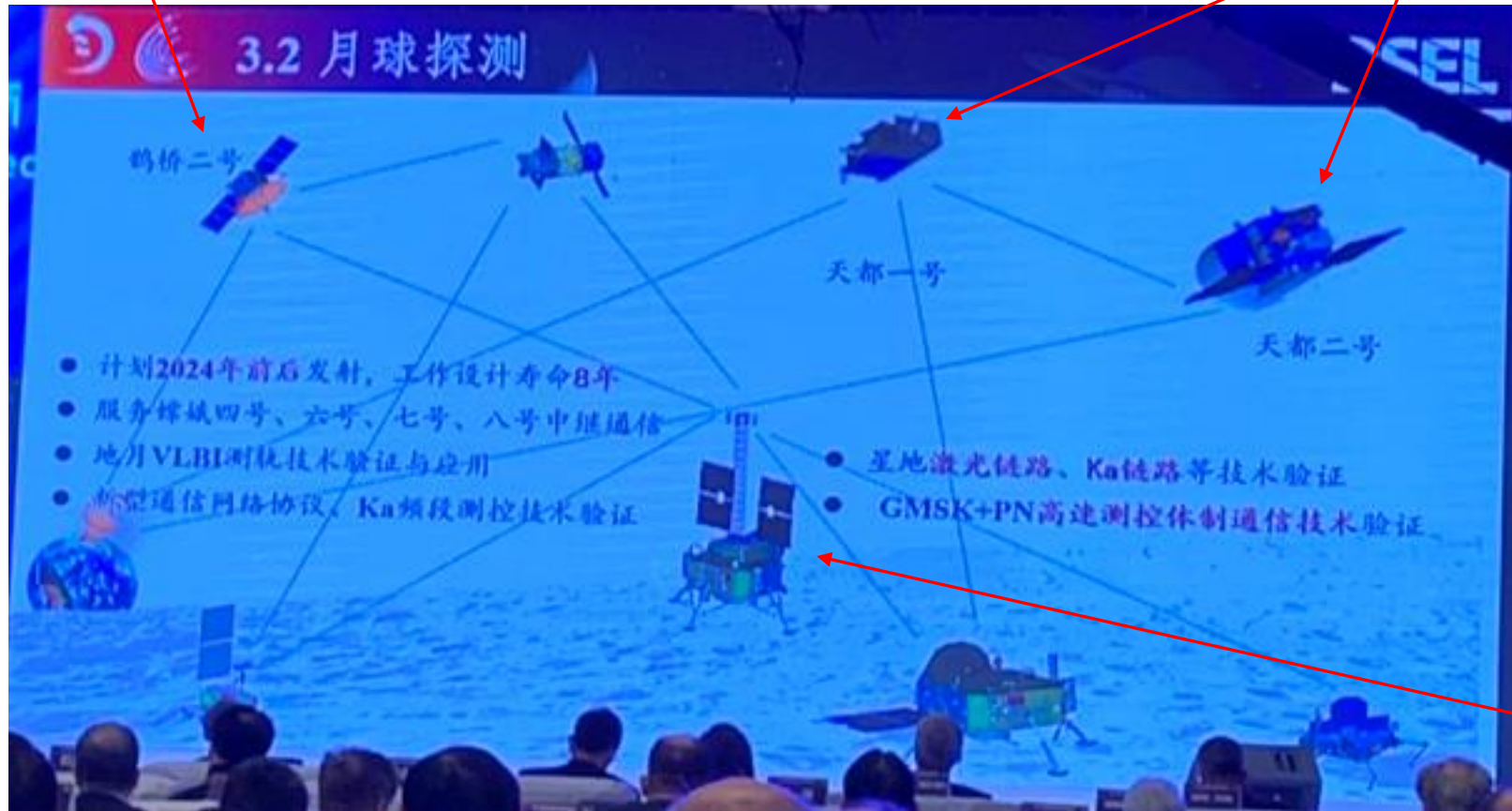


Queqiao-3 under planning

Reminding that ESA Lunar Pathfinder is currently scheduled in Q4 2025, Queqiao-2 is faster. Their schedule is as fast as NASA, showing USA and China are now in space race for the moon

Queqiao-2

Tiandu-1, 2



Chang'e 6 (in 2024), 7 (in 2026) and 8 (in 2028) robotic lunar missions

Chang'e 6 in May 2024

3.2.1 嫦娥六号

- 计划2024年5月采用长征五号运载火箭发射
- 首选着陆区为南纬43° ± 2°、东经154° ± 4°
- 开展首次月球背面采样返回

全任务约53天

探测器组合件

The diagram illustrates the mission profile of Chang'e 6, starting with the launch of the lander and ascender on the Long March 5 rocket. It shows the transfer to the Moon, the landing on the lunar surface, the collection of samples, and the subsequent ascent and return to Earth. The total mission duration is approximately 53 days.

Chang'e 7 in 2026 and Queqiao-2

3.2.2 嫦娥七号

- 计划2026年采用长征五号运载火箭发射
- 首选着陆区中心为南纬88.8°、东经123.4°
- 开展月球南极环境与资源勘查

嫦娥七号探测器

鹊桥二号

探测器任务流程示意图

The diagram shows the mission profile of Chang'e 7, including the launch of the lander and rover on the Long March 5 rocket, the transfer to the Moon, the landing on the lunar surface, and the subsequent ascent and return to Earth. The total mission duration is approximately 53 days. An arrow points to the Queqiao-2 satellite in orbit around the Moon.

3.2.3 嫦娥八号

- 计划2028年前后采用长征五号运载火箭发射
- 和嫦娥七号、鹊桥二号等一起构成月球科研站基本型

月面工作示意图

The diagram illustrates the mission profile of Chang'e 8, showing the launch of the lander and rover on the Long March 5 rocket, the transfer to the Moon, the landing on the lunar surface, and the subsequent ascent and return to Earth. The total mission duration is approximately 53 days. The diagram also shows the lunar surface work, including the deployment of the lander and rover, and the collection of samples.

Chang'e 8 in 2028 and International Lunar Research Station (ILRS) construction

Photos taken from "Report 3: Global Call & Competition for QQnet Constellation Solution", Tiandu Forum, Apr. 25, 2023.

Queqiao V2.0

总体目标：建立地月骨干链路，实现全月通信覆盖以及区域导航。

□ 骨干链路
开放式架构

□ 覆盖能力
月球南极、月球南北纬
40°以上与月背四重覆盖
全月一重覆盖

□ 拓扑架构示例 (16颗星)

- 3颗EML星 (L1)
- 3颗EML星 (L2)
- 1颗EML星 (L3)
- 2颗ELFO星
- 6颗CLO星
- 1个GEO轨道行星际中转站



Concept of QQ-Net
under study (to be
deployed before 2040)

2023.04.25-06.25
◆ 组队及线上报名

2023.07.11-07.25
◆ 建模培训 (线上)

2024.2.19-03.02
◆ 初赛全球
线上评审, 16强

2024.04.24之前
◆ 决赛现场答辩评审

2023.06.26-07.10
◆ 报名资格审核及确认

2024.2.18之前
◆ 作品提交

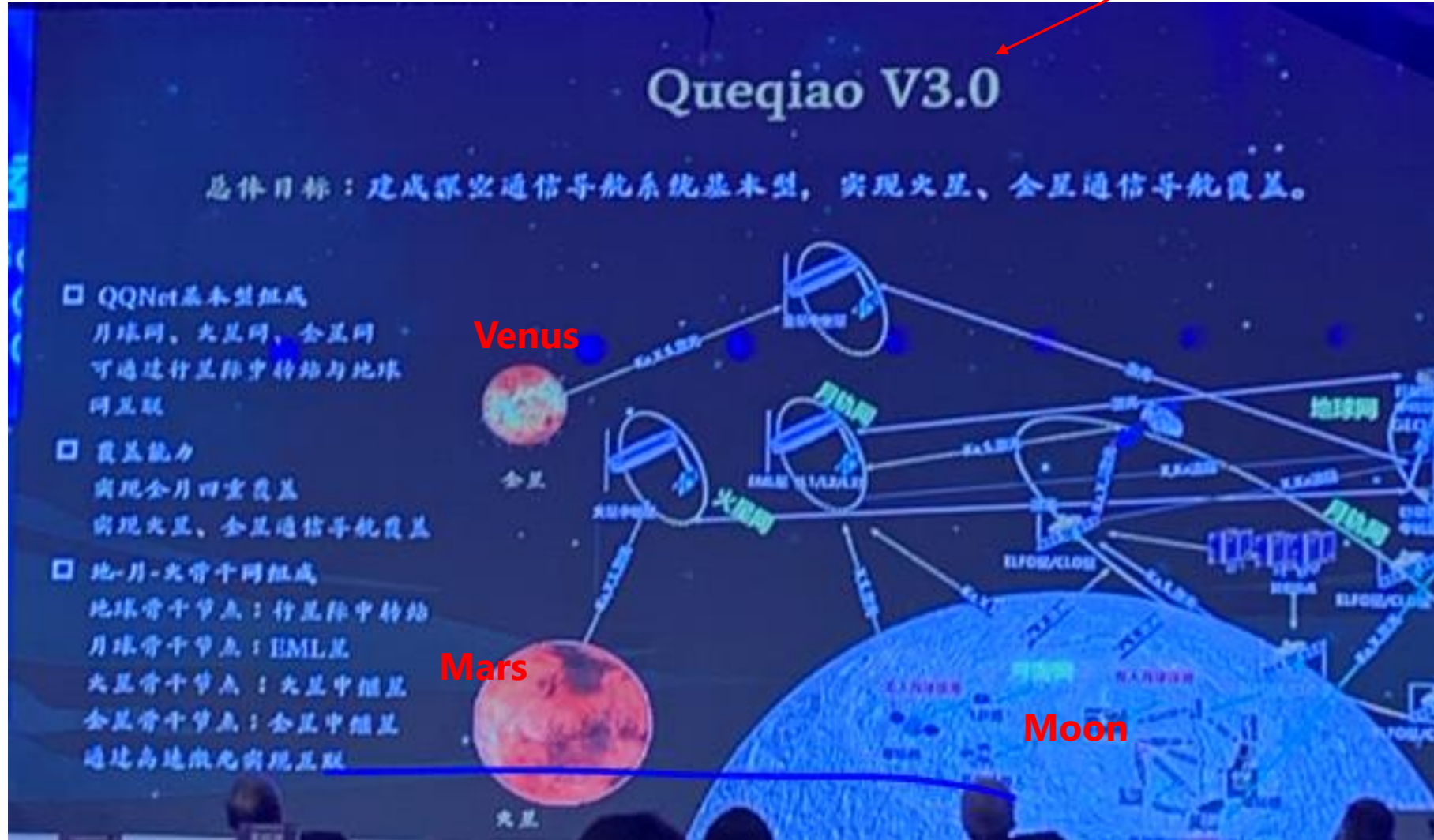
2023.03.03-04.04
◆ 决赛

2024.4
◆ 颁奖仪式
(航天日期间)

They are now in the one-year competition
study phase for the QQ-Net (2023.4-2024.4)

Photos taken from "Report 3: Global Call & Competition for QQnet
Constellation Solution", Tiandu Forum, Apr. 25, 2023. © 2023 CASC

Expansion to Mars,
Venus, ... to be realized
before 2050



International Lunar Research Station (ILRS) under planning by China and Russia. Construction starts from 2028 (by Chang'e 8) and basic model completed by 2030

4.3.1 国际月球科研站 (ILRS)

- 中国提出，多国共商、共建、共享
- 长期自主运行、短期有人参与
- 具备能源供应、中核控制、通信导航、天地往返、月面科考和地面支持等保障能力
- 持续开展科学探测研究、资源开发利用、前沿技术验证等



国际月球科研站应用型 (2050)

ILRS Cooperation Organization (ILRSCO) that is analogous to the U.S.-led Artemis program and its political underpinning, the Artemis Accords

For peaceful use, equal right, collaborative development

宗旨
和平利用、平等互利、共同发展

欢迎世界各国参与国际月球科研站大科学工程！

We welcome all countries with joint hands in the International Lunar Research Station!

4. 合作倡议——成立合作组织 (ILRSCO)

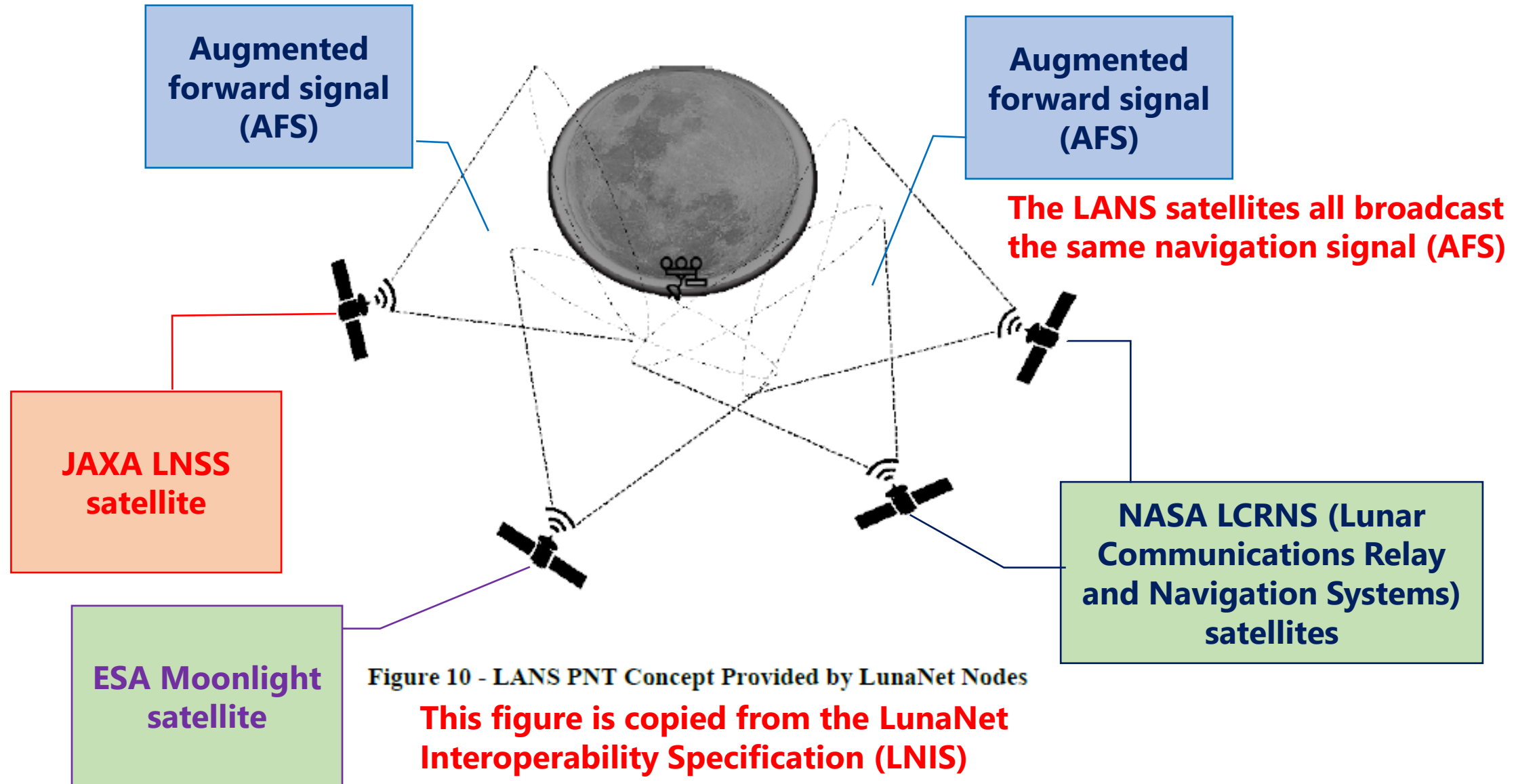
- 国际组织：参与各国共同发起成立国际月球科研站合作组织(ILRSCO)，共商、共建国际月球科研站大科学工程，共同管理科研站设施，共享科研成果。
- 创始成员：首批签约国家将作为ILRSCO创始成员，享受优先惠条件，享有更多权利，分享更多成果。
- 大科学工程总部：ILRSCO大科学工程总部将分别建设早期设计仿真、运行控制保障、数据处理、教育培训、国际交流培训等五个中心。



深空科学城概念图

We join LunaNet and its Lunar
Augmented Navigation System (LANS)
with NASA and ESA

The Lunar augmented navigation system (LANS) is the GNSS-like system for the moon



LunaNet Interoperability Specification (LNIS)

LunaNet Interoperability Specification Document

Published by NASA and ESA

Version 4

Version 4 – September 2022

The LNIS includes:

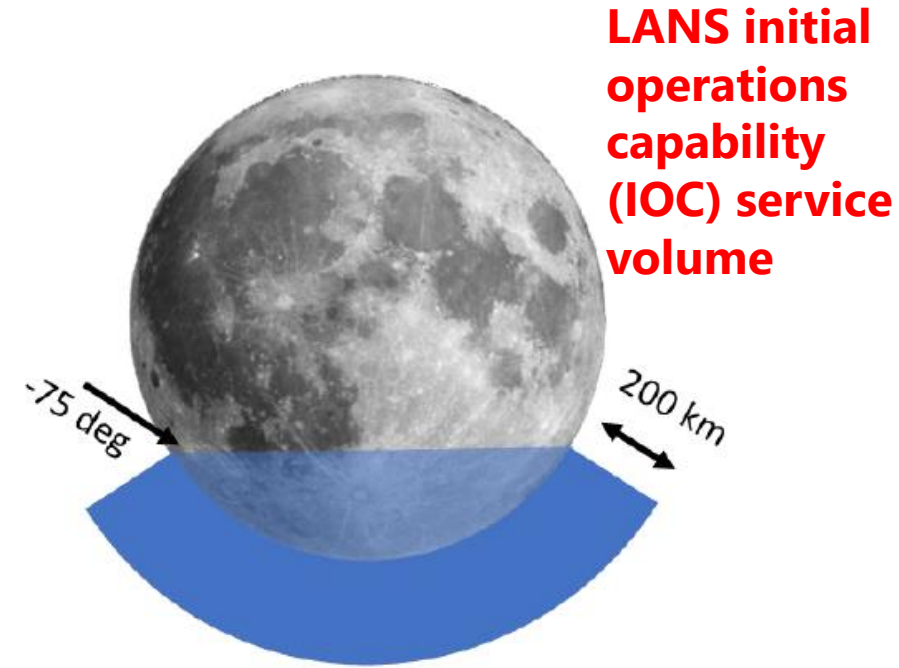
- The message format of the AFS, signal frequency, power, etc.
- The LANS Initial Operations Capability (IOC) and Enhanced Operations Capability (EOC)
- Accuracy specification (Signal-In-Space-Errors) for the LunaNet Service Providers (LNSP)
- Lunar Reference Frame Standard and Lunar Time System Standard

JAXA LNSS complies with the LNIS to be compatible and interoperable with the other LNSP such as ESA and NASA

Each LNSP shall ensure that the AFS maintains Signal-In-Space-Errors (SISEs) within the requirement specified in Table C-1 at the defined service volume

Table C-1 LNSP SISE

Error	Value
SISE pos	≤ TBD m (99%) - Calculated as the 99th percentile of the time series of instantaneous SISE values over a TBD hours period.
SISE vel	≤ TBD m/s (99%) - Calculated as the 99th percentile of the time series of instantaneous SISE values over a TBD hours period.



1. Signal-In-Space Error for positioning (SISE pos)

$$SISE_{pos} = \sqrt{(x - \tilde{x})^2 + (y - \tilde{y})^2 + (z - \tilde{z})^2 + (ct - c\tilde{t})^2},$$

Where x, y, z, t are the true position and time, while the corresponding tilde parameters represent the values broadcasted in the navigation message.

2. Signal-In-Space Error for velocity (SISE vel):

$$SISE_{vel} = \sqrt{(\dot{x} - \tilde{\dot{x}})^2 + (\dot{y} - \tilde{\dot{y}})^2 + (\dot{z} - \tilde{\dot{z}})^2 + (c\dot{t} - c\tilde{\dot{t}})^2},$$

Where $\dot{x}, \dot{y}, \dot{z}$ represents the velocity and $c\dot{t}$ the clock drift.

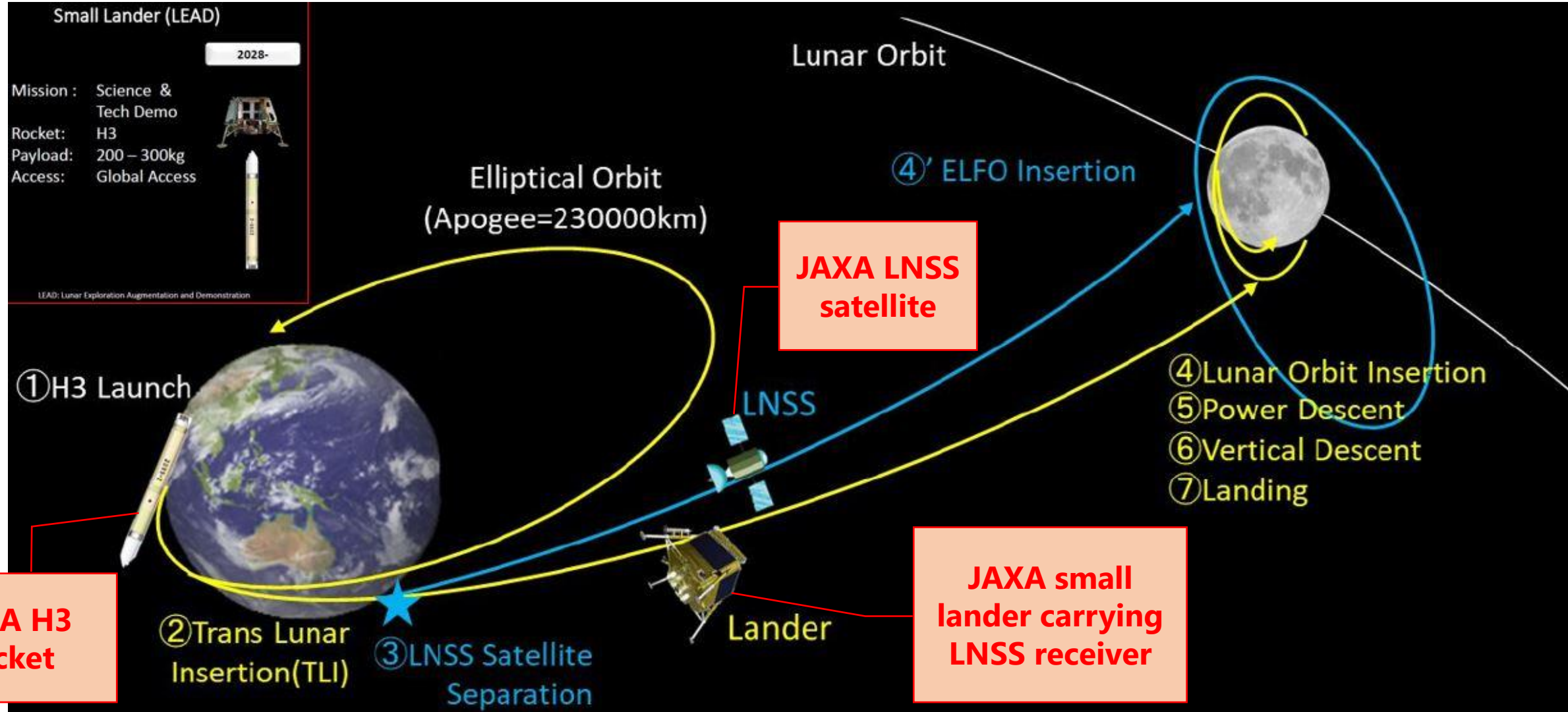
1 Figure 11 - LANS IOC Service Coverage and Performance Volume



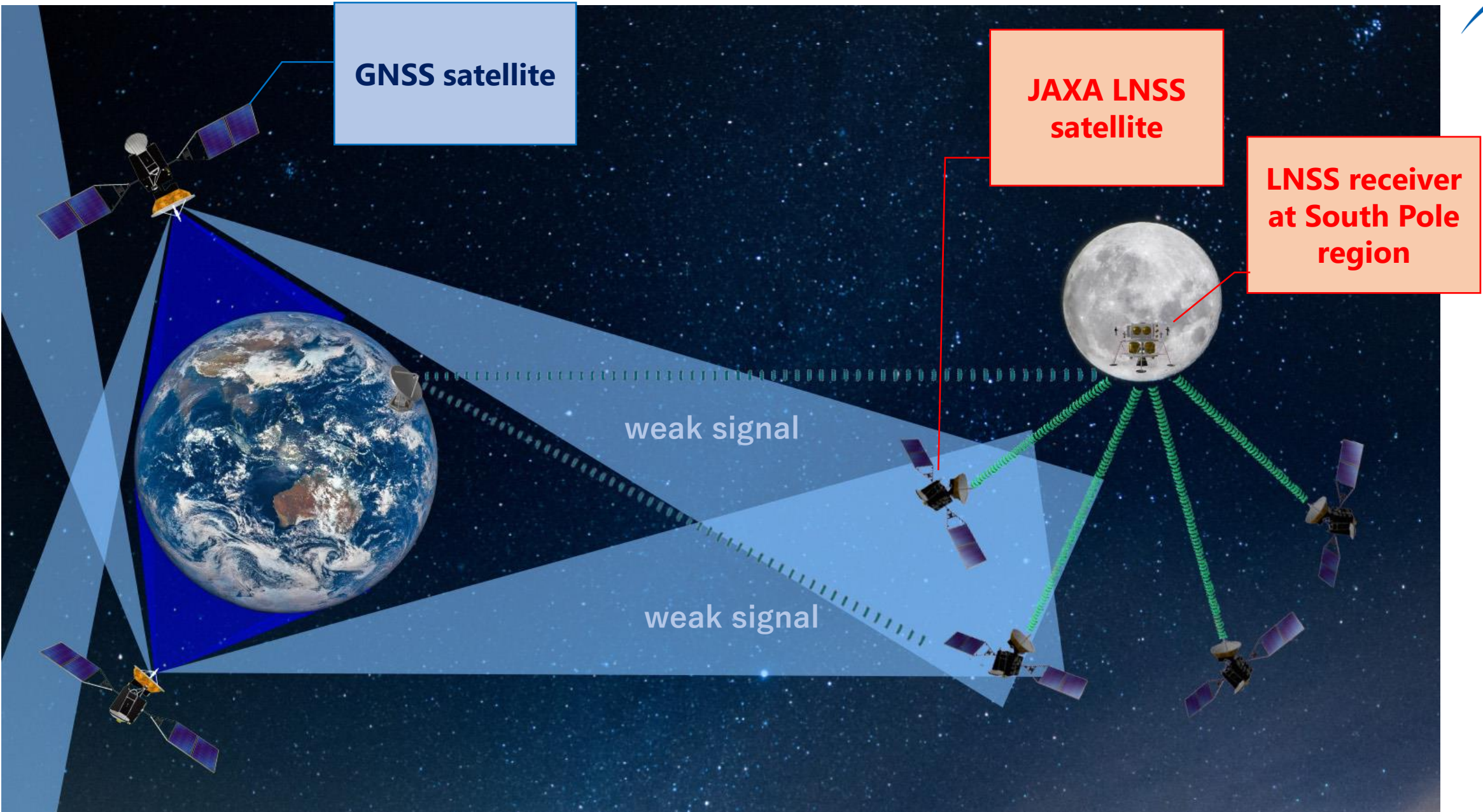
Both SISEs are based on lunar reference frame and time, which will be defined in the applicable documents to the LNIS called Lunar Reference Frame Standard and Lunar Time System Standard

Our LNSS Demonstration Mission Under Planning

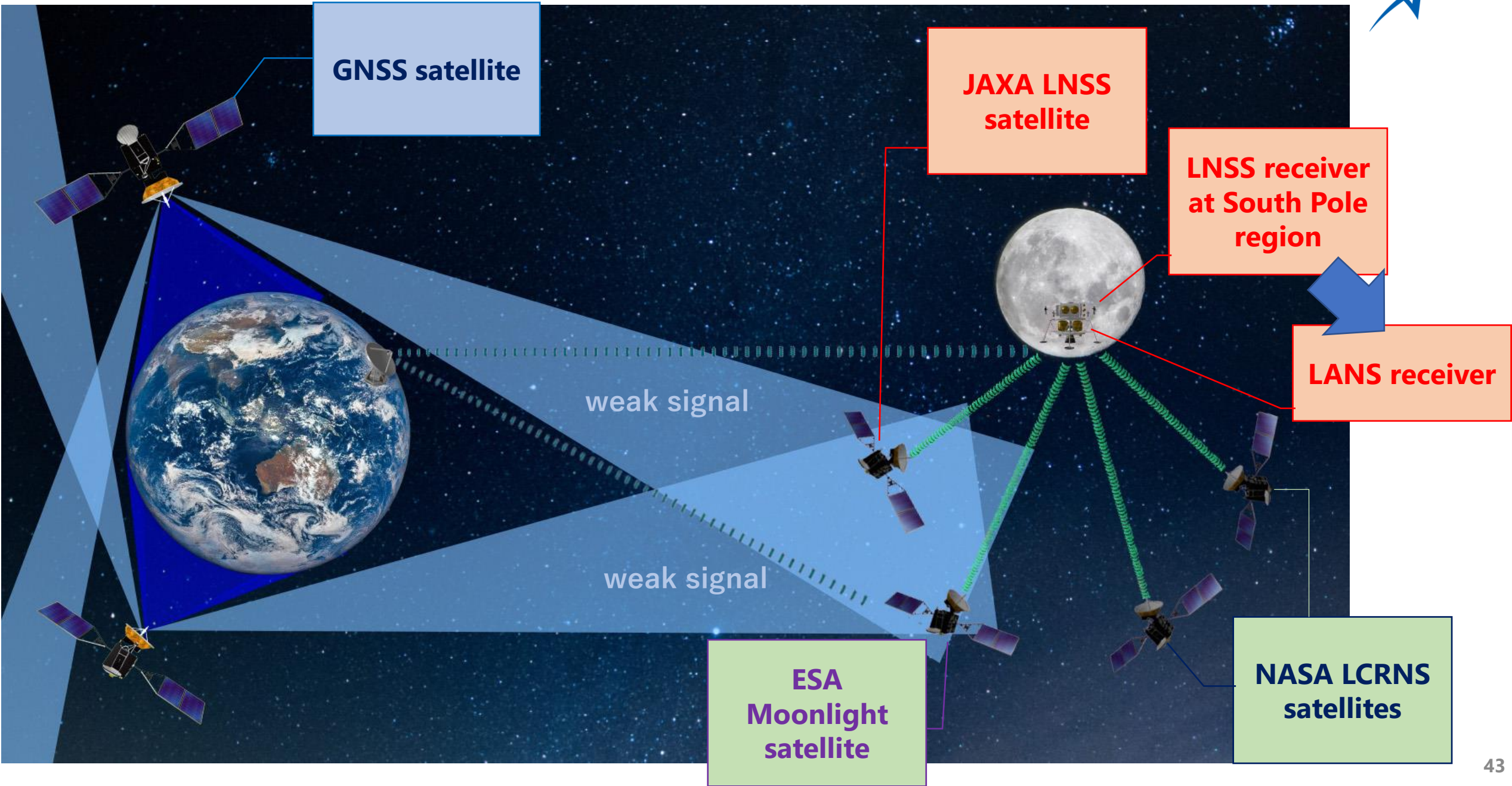
LNSS demonstration mission targeting around 2028



We deploy **one LNSS satellite** and **one LNSS receiver** at South Pole region



Proposing first-ever lunar PNT SISE evaluation and **interoperability** demonstration



Conclusions

- **The JAXA LNSS will comply with the LunaNet Interoperability Specification (LNIS) and join the Lunar Augmented Navigation System (LANS) that becomes the moon GNSS.**
- **We are planning our demonstration mission around 2028 and our receiver to be located at South Pole region will be interoperable so that all LunaNet Service Providers (LNSPs) Augmented Forward Signals (AFSs) will be received.**
- **I believe this demonstration mission will contribute to the SISE evaluation for all LNSPs such as NASA, ESA, and JAXA joining the LANS. Related collaboration discussion has been already ongoing both bilaterally and multilaterally.**

Discussion ongoing with foreign colleagues



International Committee on
Global Navigation Satellite Systems



NASA GNSS Activities Update; *Joel PARKER, NASA/United States*

Lunar Navigation Satellite System (LNSS) and its Demonstration Mission; *MASAYA Murata, JAXA/Japan*

The Envision of Earth-Moon Communication-Navigation System; *Xiongwen HE, CAST/China*

ESA Lunar Navigation Plans: Lunar Pathfinder & Moonlight; *Javier VENTURA-TRAVESET, ESA*

**Lunar PNT presentation
from NASA, ESA, JAXA,
CAST
(On respective space
agency's lunar PNT system)**



Committee for
the Study of
LunaNet
Governance

Lunar Communications
& Navigation Working
Group (LCNWG)



This year's ION GNSS+2023 Lunar PNT panel


<https://www.ion.org/gnss/sessions.cfm?sessionID=1596>

Session F5b: PANEL: International Civilian Agency Lunar PNT Systems

RETURN TO SESSION LIST

Date: Friday, September 15, 2023

Time: 10:35 a.m. - 12:15 p.m.

 **ON DEMAND** This session will be recorded, and will become available for viewing by registered attendees within 24 hours.

Session Chairs



Dr. Evan Anzalone
NASA



Giuseppe D'Amore
*Agenzia Spaziale
Italiana*

Track Chair



Dr. Seebany Datta-Barua
Illinois Institute of Technology

Panel Members:

- Dr. Javier Ventura-Traveset, European Space Agency (ESA)
- Cheryl Gramling, National Aeronautics and Space Administration (NASA)
- Dr. Masaya Murata, Japan Aerospace Exploration Agency (JAXA) (invited)

} **ESA Moonlight
NASA LCRNS
JAXA LNSS**

**We are partners, working
together towards the
moon GNSS (LANS)**

Thanks!

Masaya Murata (JAXA)
murata.masaya@jaxa.jp

